

Contents

1. Warnings	3
2. Introduction	4
2.1. Feature List	4
2.2. Type Code	5
3. Mechanical Installation	6
3.1. Mechanical Installation.....	6
3.2. Dimensions and Weights.....	7
4. Electrical Installation	8
4.1. Control Wiring.....	8
4.2. Control Terminals	8
4.3. Remote Inputs	8
4.4. Serial Communication	9
4.5. Earth Terminal	9
4.6. Power Terminations.....	9
4.7. Motor Connection	10
4.8. In-Line Installation	10
4.9. Inside Delta Installation	12
4.10. Current Ratings	14
4.11. Minimum and Maximum Current Settings.....	18
4.12. Bypass Contactor.....	18
4.13. Main Contactor	18
4.14. Circuit Breaker	18
4.15. Power Factor Correction	18
4.16. Fuses	19
4.17. Schematic Diagrams	23
5. Application Examples	25
5.1. Motor Overload Protection.....	25
5.2. AAC Adaptive Acceleration Control	25
5.3. Starting Modes.....	25
5.4. Stopping Modes	27
5.5. Jog Operation	29
5.6. Inside Delta Operation	29
5.7. Installation with Main Contactor.....	30
5.8. Installation with Bypass Contactor	31
5.9. Emergency Run Operation.....	32
5.10. Auxiliary Trip Circuit.....	33
5.11. Soft Braking	34
5.12. Two Speed Motor	36
6. Operation	38
6.2. The LCP.....	38
6.3. Local Control Buttons.....	38
6.4. Displays.....	38

7. Programming	41
7.1. Access Control	41
7.2. Quick Menu	41
7.3. Main Menu.....	44
7.4. 1 – Primary Motor Settings	47
7.5. 2 – Protection	50
7.6. 3 – Inputs.....	53
7.7. 4 – Outputs	55
7.8. 5 – Start/Stop Timers	57
7.9. 6 – Auto-Reset.....	58
7.10. 7 – Secondary Motor Set	59
7.11. 8 – Display.....	61
7.12. 15 – Restricted Parameters.....	63
7.13. 16 – Protection Action.....	64
7.14. 20 – Factory Parameters	65
8. Tools.....	66
8.1. Set Date and Time	66
8.2. Load/Save Settings.....	66
8.3. Reset Thermal Model.....	67
8.4. Protection Simulation.....	67
8.5. Output Signal Simulation.....	68
8.6. Digital I/O State	68
8.7. Temp Sensors State	68
8.8. Alarm Log.....	68
9. Troubleshooting.....	70
9.1. Trip Messages.....	70
9.2. General Faults.....	73
10. Specifications.....	75
10.1. Accessories	76
10.2. Model Selection	77

1. Warnings

When reading this manual you will come across different symbols that require special attention. The symbols used are the following:



NB!:

Indicates something to be noted by the reader



Indicates a general warning



Indicates a high voltage warning

The examples and diagrams in this manual are included solely for illustrative purposes. The information contained in this manual is subject to change at any time and without prior notice. In no event will responsibility or liability be accepted for direct, indirect or consequential damages resulting from the use or application of this equipment.



MCD 500 soft starters contain dangerous voltages when connected to mains voltage. Only a competent electrician should carry out the electrical installation. Improper installation of the motor or the soft starter may cause equipment failure, serious injury or death. Follow this manual and local electrical safety codes.



Disconnect the soft starter from mains voltage before carrying out repair work.

It is the responsibility of the user or person installing the soft starter to provide proper grounding and branch circuit protection according to local electrical safety codes.

Do not connect power factor correction capacitors to the output of MCD 500 soft starters. If static power factor correction is employed, it must be connected to the supply side of the soft starter.

The motor can be stopped by means of digital or bus commands while the soft starter is connected to the mains, if the soft starter is in Auto On mode.

1. If personal safety considerations make it necessary to ensure that no unintended start occurs, these stop functions are not sufficient.
2. A motor that has been stopped may start if faults occur in the electronics of the soft starter, or a temporary fault in the supply mains or the motor connection ceases.



AUTO-START

Use the auto-start feature with caution. Read all the notes related to auto-start before operation.



Equipment containing electrical components may not be disposed of together with domestic waste.

It must be collected separately as electrical and electronic waste according to local and currently valid legislation.

2. Introduction

The MCD 500 is an advanced digital soft start solution for motors from 7 kW to 800 kW. MCD 500 soft starters provide a complete range of motor and system protection features and have been designed for reliable performance in the most demanding installation situations.

2.1. Feature List

Models for all connection requirements

- 21 A to 1600 A (in-line connection)
- In-line or inside delta connection
- Internally bypassed up to 215 A
- Mains voltage: 200~525 VAC or 380~690 VAC
- Control voltage: 24 VAC/VDC, 110~120 VAC or 220~240 VAC

User-friendly LCP

- Loggings
- Real-time graphs
- SCR conduction bar graph

Tools

- Application setups
- Date and time stamped event log with 99 entries
- 8 most recent trips
- Counters
- Protection simulation
- Output signal simulation

Inputs and outputs

- Local or remote control input options (3 x fixed 1 x programmable)
- Relay outputs (3 x programmable)
- Analog programmable output
- 24 VDC 200 mA supply output

Start and run modes

- AAC - Adaptive Acceleration Control
- Constant current
- Current ramp
- Kickstart
- Jog
- Emergency run operation

Stop Modes

- AAC - Adaptive Acceleration Control
- Timed voltage ramp soft stop
- DC brake
- Soft brake
- Emergency stop

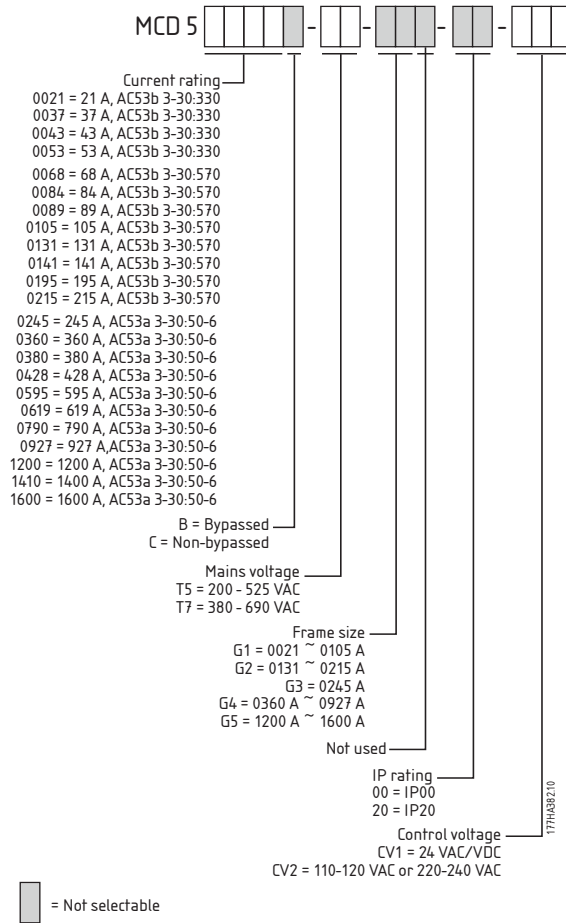
Other features

- Auto start/stop timer
- Second order thermal model
- Battery backup of clock and thermal model
- Optional DeviceNet, Modbus or Profibus communication modules

Comprehensive protection

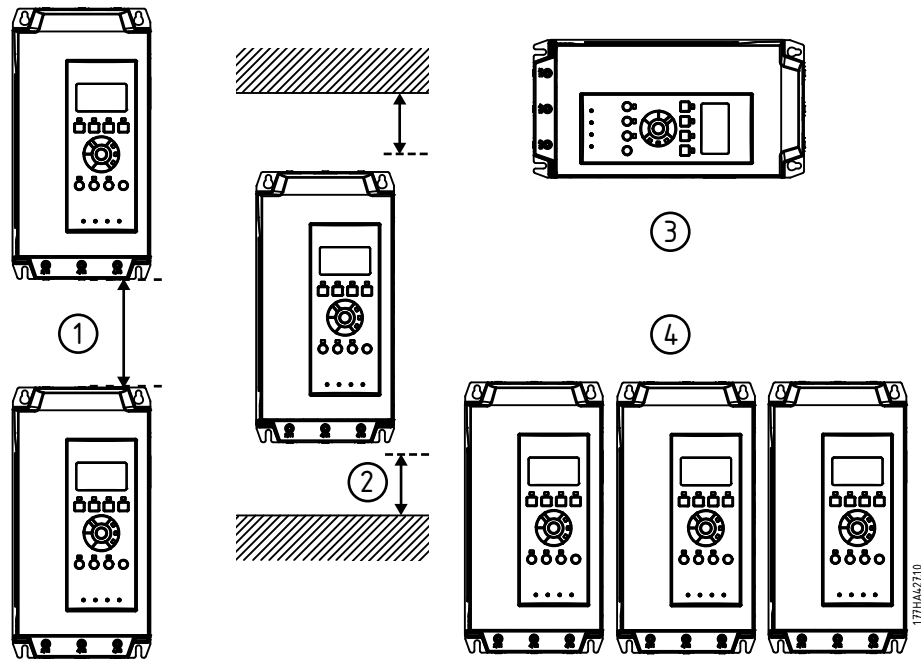
- Wiring/Connection/Supply
 - Motor connection
 - Phase sequence
 - Power loss
 - Individual phase loss
 - Mains frequency
- Current
 - Excess start time
 - Current imbalance
 - Undercurrent
 - Instantaneous overcurrent
- Thermal
 - Motor thermistor
 - Motor overload
 - Bypass relay overload
 - Heatsink temperature
- Communication
 - Network comms
 - Starter comms
- External
 - Input trip
- Starter
 - Individual shorted SCR
 - Battery/Clock

2.2. Type Code



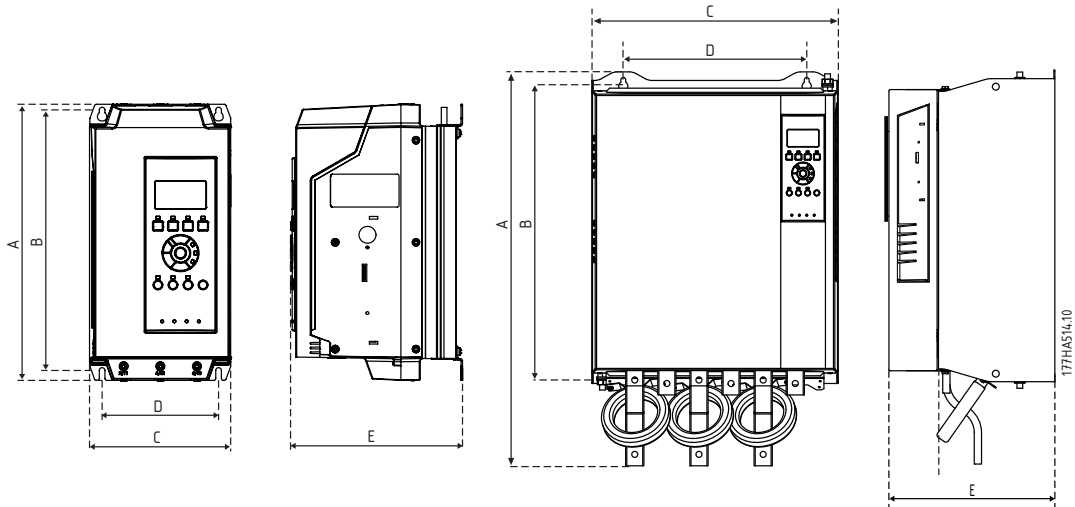
Mechanical Installation

3.1. Mechanical Installation



1	MCD5-0021B ~ MCD5-0245C: Allow 100 mm (3.94 inches) between soft starters. MCD5-0360C ~ MCD5-1600C: Allow 200 mm (7.88 inches) between soft starters.
2	MCD5-0021B ~ MCD5-0215B: Allow 50 mm (1.97 inches) between the soft starter and solid surfaces. MCD5-0245C: Allow 100 mm (3.94 inches) between the soft starter and solid surfaces. MCD5-0360C ~ MCD5-1600C: Allow 200 mm (7.88 inches) between the soft starter and solid surfaces.
3	The soft starter may be mounted on its side. Derate the soft starter's rated current by 15%.
4	Soft starters may be mounted side by side with clearance of 50 mm (1.97 inches) on both sides.

3.2. Dimensions and Weights



Model	A mm (inches)	B mm (inches)	C mm (inches)	D mm (inches)	E mm (inches)	Weight kg (lbs)
MCD5-0021B						4.2 (9.3)
MCD5-0037B						
MCD5-0043B						
MCD5-0053B	295	278	150	124	183	4.5 (9.9)
MCD5-0068B	(11.6)	(10.9)	(5.9)	(4.9)	(7.2)	
MCD5-0084B						
MCD5-0089B						4.9 (10.8)
MCD5-0105B						
MCD5-0131B						14.9 (32.8)
MCD5-0141B	438	380	275	248	250	
MCD5-0195B	(17.2)	(15.0)	(10.8)	(9.8)	(9.8)	
MCD5-0215B						
MCD5-0245C	460	400	390	320	279	23.9 (52.7)
	(18.1)	(15.7)	(15.4)	(12.6)	(11.0)	
MCD5-0360C						50.1 (110.5)
MCD5-0380C						
MCD5-0428C	689	520	430	320	302	53.1 (117.1)
MCD5-0595C	(27.1)	(20.5)	(16.9)	(12.6)	(11.9)	
MCD5-0619C						
MCD5-0790C						
MCD5-0927C						
MCD5-1200C	856	727	585	500	364	120 (264.6)
MCD5-1410C	(33.7)	(28.6)	(23.0)	(19.7)	(14.3)	
MCD5-1600C						

4. Electrical Installation

4.1. Control Wiring

The soft starter can be controlled in three ways:

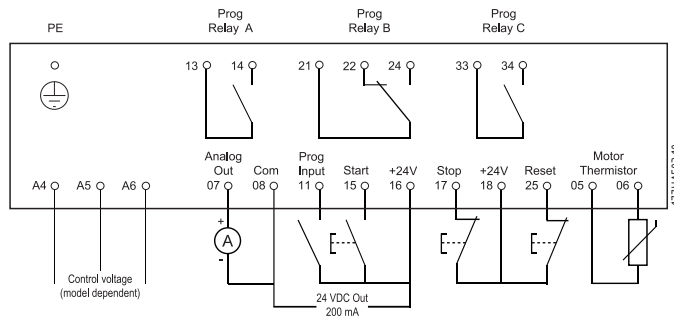
- using the buttons on the LCP
- via remote inputs
- via a serial communication link

The MCD 500 will always respond to a local start or stop command (via the **HAND ON** and **OFF** buttons on the LCP). Pressing the **AUTO ON** button selects remote control (the MCD 500 will accept commands from the remote inputs). In remote mode, the Auto On LED will be on. In local mode, the Hand On LED will be on if the MCD 500 is starting or running and the Off LED will be on if the MCD 500 is stopped or stopping.

4.2. Control Terminals

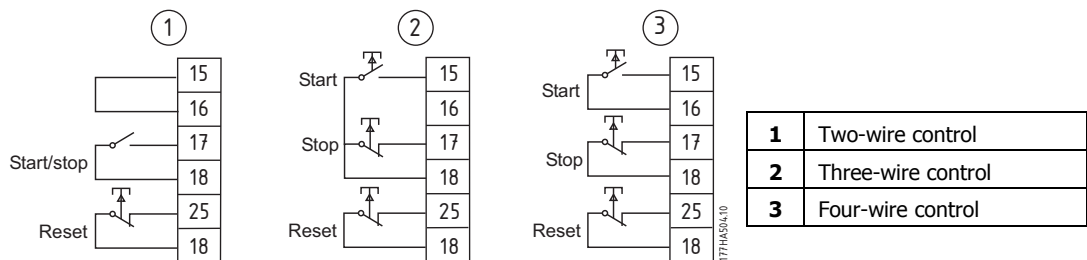
Control terminations use 2.5mm² plug-in terminal blocks. Different models require control voltage to different terminals:

- | | |
|-------------------|--------|
| CV1 (24 VAC/VDC) | A5, A6 |
| CV2 (110~120 VAC) | A5, A6 |
| CV2 (220~240 VAC) | A4, A6 |



4.3. Remote Inputs

The MCD 500 has three fixed inputs for remote control. These inputs should be controlled by contacts rated for low voltage, low current operation (gold flash or similar).



The reset input can be normally open or normally closed. Use parameter 3-8 to select the configuration.



Do not apply voltage to the control input terminals. These are active 24 VDC inputs and must be controlled with potential free contacts.

Cables to the control inputs must be segregated from mains voltage and motor cabling.

4.4. Serial Communication

Serial communication is always enabled in local control mode, and can be enabled or disabled in remote control mode (=> Par. 3-2).

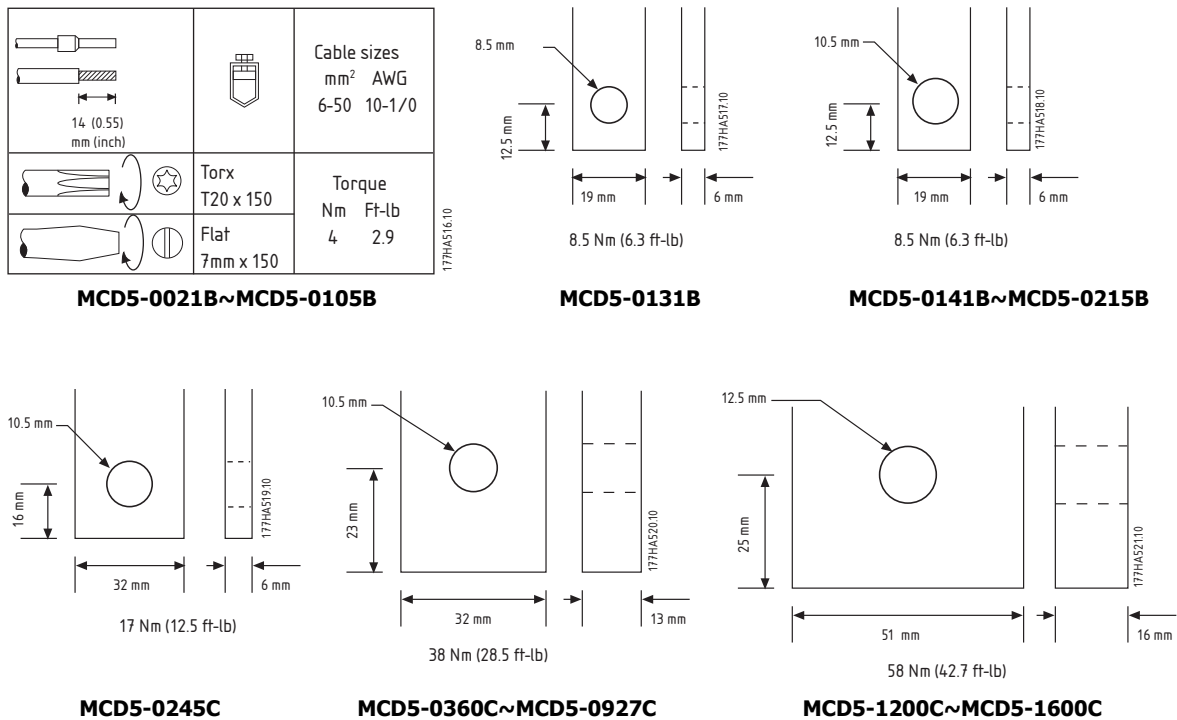
4.5. Earth Terminal

Earth terminals are located at the back of the soft starter.

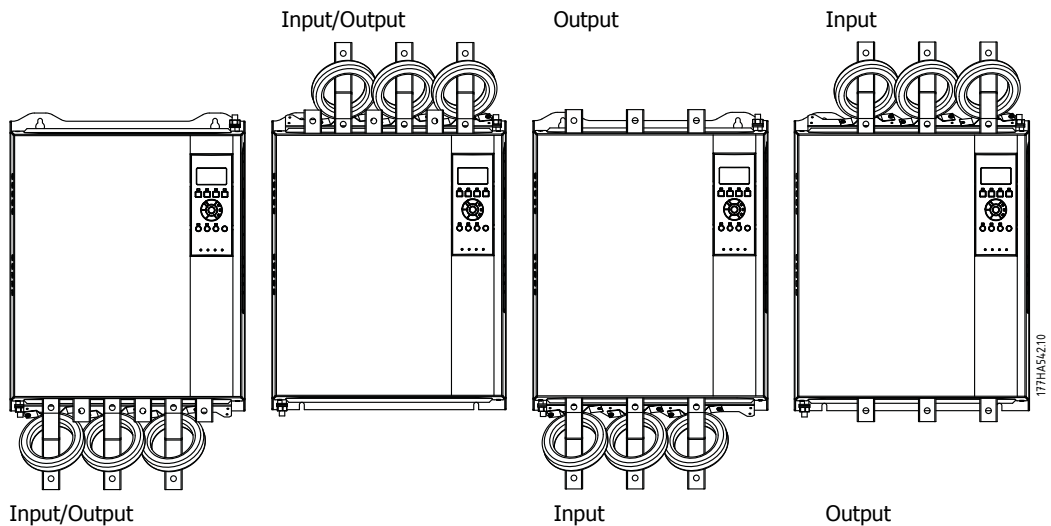
- MCD5-0021B ~ MCD5-0105B have one terminal, on the input side.
- MCD5-0131C ~ MCD5-1600C have two terminals, one on the input side and one on the output side.

4.6. Power Terminations

Use only copper stranded or solid conductors, rated for 75° C.



The bus bars on models MCD5-0360C ~ MCD5-1600C can be adjusted for top or bottom input and output as required. For step-by-step instructions on adjusting the bus bars, refer to the supplied insert.



4.7. Motor Connection

MCD 500 soft starters can be connected to the motor in-line or inside delta (also called three-wire and six-wire connection). The MCD 500 will automatically detect the motor connection and perform the necessary calculations internally, so it is only necessary to program the motor full load current (Par. 1-1).



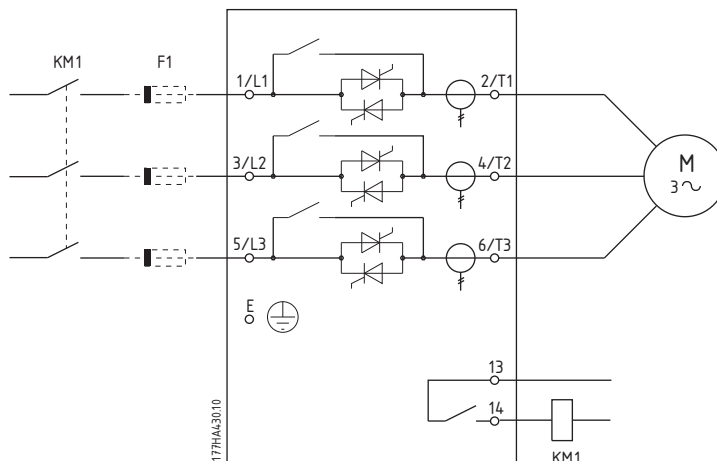
NB!:

For personnel safety, the power terminals on models up to MCD5-0105B are protected by snap-off tabs. When using large cables, it may be necessary to break off these tabs.

Models which are internally bypassed do not require an external bypass contactor.

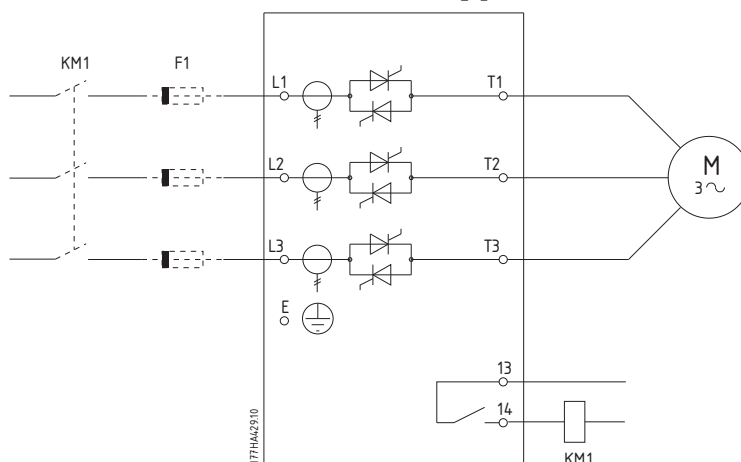
4.8. In-Line Installation

4.8.1. In-line installation, internally bypassed



KM1	Main contactor (optional)
F1	Fuses (optional)

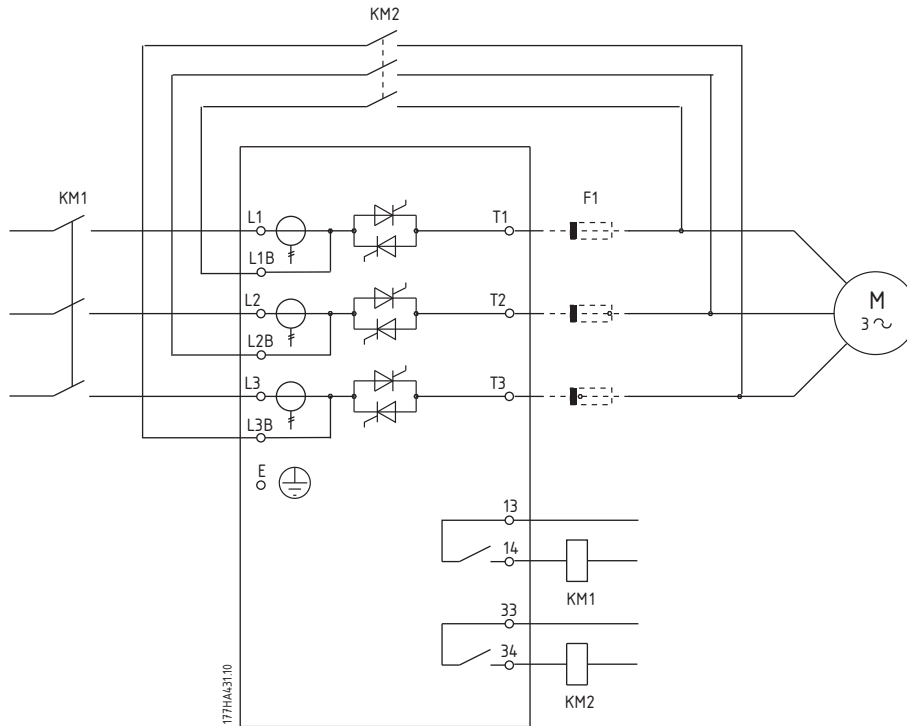
4.8.2. In-line installation, non-bypassed



KM1	Main contactor (optional)
F1	Fuses (optional)

4.8.3. In-line installation, externally bypassed

Non-bypassed models have dedicated bypass terminals, which allow the EMX3 to continue providing protection and monitoring functions even when bypassed via an external bypass contactor. The bypass contactor must be connected to the bypass terminals and controlled by a programmable output configured to Run (=> Par. 4-1~4-9).



KM1	Main contactor
KM2	Bypass contactor
F1	Fuses (optional)



NB!:

The bypass terminals on MCD5-0245C are T1B, T2B, T3B. The bypass terminals on MCD5-0360C ~ MCD5-1600C are L1B, L2B, L3B.

The fuses can be installed on the input side if required.

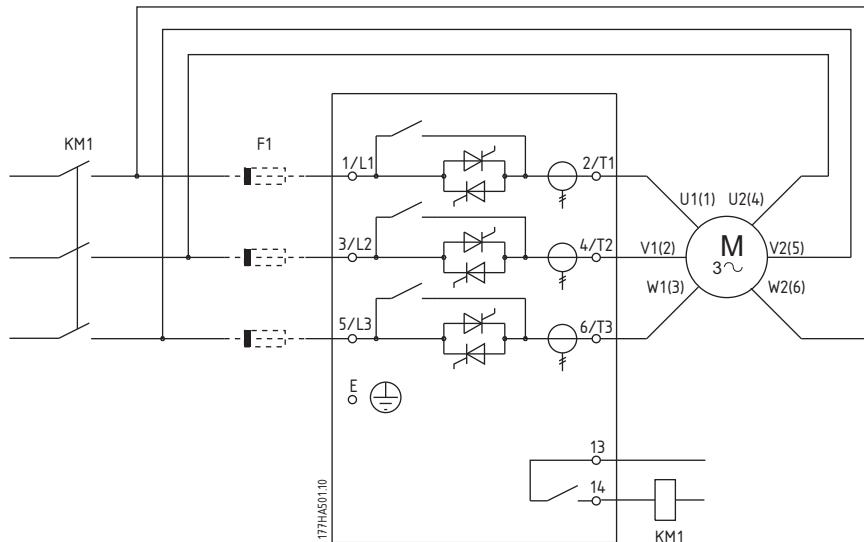
4.9. Inside Delta Installation



N.B.!

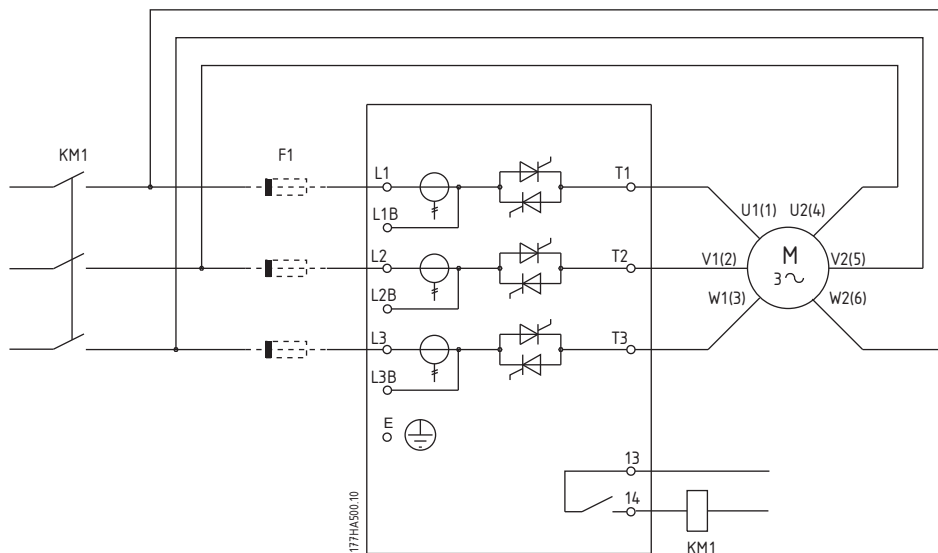
When connecting the MCD 500 in inside delta configuration, always install a main contactor or shunt trip circuit breaker.

4.9.1. Inside delta installation, internally bypassed



KM1	Main contactor
F1	Fuses (optional)

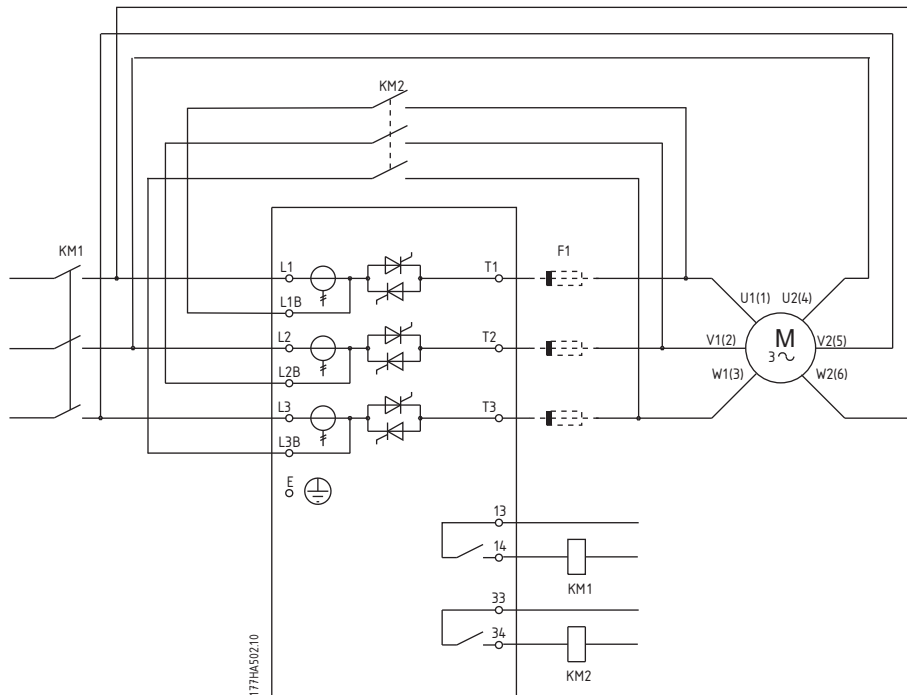
4.9.2. Inside delta installation, non-bypassed



KM1	Main contactor
F1	Fuses (optional)

4.9.3. Inside delta installation, externally bypassed

Non-bypassed models have dedicated bypass terminals, which allow the EMX3 to continue providing protection and monitoring functions even when bypassed via an external bypass contactor. The bypass contactor must be connected to the bypass terminals and controlled by a programmable output configured to Run (=> Par. 4-1~4-9).



KM1	Main contactor
KM2	Bypass contactor
F1	Fuses (optional)



NB!:

The bypass terminals on MCD5-0245C are T1B, T2B, T3B. The bypass terminals on MCD5-0360C ~ MCD5-1600C are L1B, L2B, L3B.

The fuses can be installed on the input side if required.

4.10. Current Ratings

Contact your local supplier for ratings under operating conditions not covered by these ratings charts.

All ratings are calculated at altitude of 1000 metres and ambient temperature of 40 °C.

4.10.1. In-line connection (bypassed)



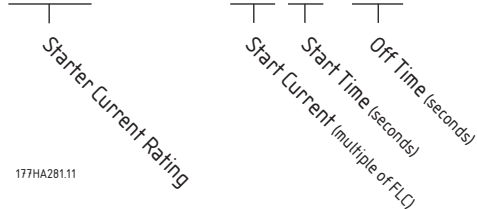
NB!:

Models MCD5-0021B~MCD5-0215B are internally bypassed. Models MCD5-0245C~MCD5-1600C require an external bypass contactor.

	AC-53b 3-30:330	AC-53b 4-20:340	AC-53b 4.5-30:330
MCD5-0021B	21 A	17 A	15 A
MCD5-0037B	37 A	31 A	26 A
MCD5-0043B	43 A	37 A	30 A
MCD5-0053B	53 A	46 A	37 A
	AC-53b 3-30:570	AC-53b 4-20:580	AC-53b 4.5-30:570
MCD5-0068B	68 A	55 A	47 A
MCD5-0084B	84 A	69 A	58 A
MCD5-0089B	89 A	74 A	61 A
MCD5-0105B	105 A	95 A	78 A
MCD5-0131B	131 A	106 A	90 A
MCD5-0141B	141 A	121 A	97 A
MCD5-0195B	195 A	160 A	134 A
MCD5-0215B	215 A	178 A	148 A
MCD5-0245C	255 A	201 A	176 A
MCD5-0360C	360 A	310 A	263 A
MCD5-0380C	380 A	359 A	299 A
MCD5-0428C	430 A	368 A	309 A
MCD5-0595C	620 A	540 A	434 A
MCD5-0619C	650 A	561 A	455 A
MCD5-0790C	790 A	714 A	579 A
MCD5-0927C	930 A	829 A	661 A
MCD5-1200C	1200 A	1200 A	1071 A
MCD5-1410C	1410 A	1319 A	1114 A
MCD5-1600C	1600 A	1600 A	1353 A

4.10.2. AC-53 rating for bypassed operation

141 A: AC-53b: 4.5-30 : 570



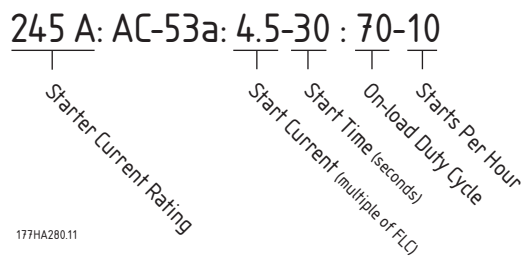
177HA281.11

All ratings are calculated at altitude of 1000 metres and ambient temperature of 40 °C.

4.10.3. In-line connection (non-bypassed/continuous)

	AC-53a 3-30:50-6	AC-53a 4-20:50-6	AC-53a 4.5-30:50-6
MCD5-0245C	245 A	195 A	171 A
MCD5-0360C	360 A	303 A	259 A
MCD5-0380C	380 A	348 A	292 A
MCD5-0428C	428 A	355 A	300 A
MCD5-0595C	595 A	515 A	419 A
MCD5-0619C	619 A	532 A	437 A
MCD5-0790C	790 A	694 A	567 A
MCD5-0927C	927 A	800 A	644 A
MCD5-1200C	1200 A	1135 A	983 A
MCD5-1410C	1410 A	1187 A	1023 A
MCD5-1600C	1600 A	1433 A	1227 A

4.10.4. AC-53 rating for continuous operation



All ratings are calculated at altitude of 1000 metres and ambient temperature of 40 °C.

4.10.5. Inside delta connection (bypassed)

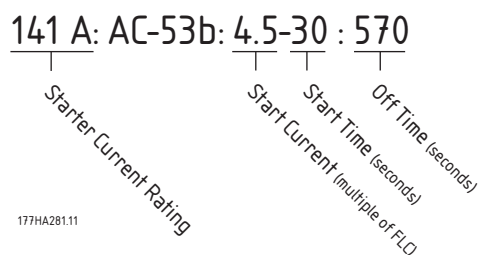


NB!:

Models MCD5-0021B~MCD5-0215B are internally bypassed. Models MCD5-0245C~MCD5-1600C require an external bypass contactor.

	AC-53b 3-10:350	AC-53b 3.5-15:345	AC-53b 4.5-30:340
MCD5-0021B	32 A	26 A	22 A
MCD5-0037B	56 A	47 A	39 A
MCD5-0043B	65 A	56 A	45 A
MCD5-0053B	80 A	69 A	55 A
	AC-53b 3-10:590	AC-53b 3.5-15:585	AC-53b 4.5-30:580
MCD5-0068B	102 A	83 A	71 A
MCD5-0084B	126 A	104 A	87 A
MCD5-0089B	134 A	112 A	92 A
MCD5-0105B	158 A	143 A	117 A
MCD5-0131B	197 A	159 A	136 A
MCD5-0141B	212 A	181 A	146 A
MCD5-0195B	293 A	241 A	201 A
MCD5-0215B	323 A	268 A	223 A
MCD5-0245C	383 A	302 A	264 A
MCD5-0360C	540 A	465 A	395 A
MCD5-0380C	570 A	539 A	449 A
MCD5-0428C	645 A	552 A	463 A
MCD5-0595C	930 A	810 A	651 A
MCD5-0619C	975 A	842 A	683 A
MCD5-0790C	1185 A	1072 A	869 A
MCD5-0927C	1395 A	1244 A	992 A
MCD5-1200C	1800 A	1800 A	1607 A
MCD5-1410C	2115 A	1979 A	1671 A
MCD5-1600C	2400 A	2400 A	2030 A

4.10.6. AC-53 rating for bypassed operation

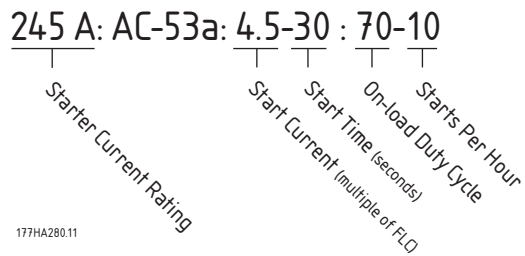


All ratings are calculated at altitude of 1000 metres and ambient temperature of 40 °C.

4.10.7. Inside delta connection (non-bypassed/continuous)

	AC-53a 3-30:50-6	AC-53a 4-20:50-6	AC-53a 4.5-30:50-6
MCD5-0245C	368 A	293 A	257 A
MCD5-0360C	540 A	455 A	389 A
MCD5-0380C	570 A	522 A	438 A
MCD5-0428C	643 A	533 A	451 A
MCD5-0595C	893 A	773 A	629 A
MCD5-0619C	929 A	798 A	656 A
MCD5-0790C	1185 A	1042 A	851 A
MCD5-0927C	1391 A	1200 A	966 A
MCD5-1200C	1800 A	1702 A	1474 A
MCD5-1410C	2115 A	1780 A	1535 A
MCD5-1600C	2400 A	2149 A	1841 A

4.10.8. AC-53 rating for continuous operation



All ratings are calculated at altitude of 1000 metres and ambient temperature of 40 °C.

4.11. Minimum and Maximum Current Settings

The MCD 500's minimum and maximum full load current settings depend on the model:

Model	In-line connection		Inside delta connection	
	Minimum	Maximum	Minimum	Maximum
MCD5-0021B	4 A	23 A	6 A	34 A
MCD5-0037B	8 A	43 A	12 A	64 A
MCD5-0043B	10 A	50 A	15 A	75 A
MCD5-0053B	10 A	53 A	15 A	79 A
MCD5-0068B	15 A	76 A	22 A	114 A
MCD5-0084B	19 A	97 A	28 A	145 A
MCD5-0089B	20 A	100 A	30 A	150 A
MCD5-0105B	21 A	105 A	31 A	157 A
MCD5-0131B	29 A	145 A	43 A	217 A
MCD5-0141B	34 A	170 A	51 A	255 A
MCD5-0195B	40 A	200 A	60 A	300 A
MCD5-0215B	44 A	220 A	66 A	330 A
MCD5-0245C	51 A	255 A	76 A	382 A
MCD5-0360C	72 A	360 A	108 A	540 A
MCD5-0380C	38 A	380 A	57 A	570 A
MCD5-0428C	43 A	430 A	64 A	645 A
MCD5-0595C	62 A	620 A	93 A	930 A
MCD5-0619C	65 A	650 A	97 A	975 A
MCD5-0790C	79 A	790 A	118 A	1185 A
MCD5-0927C	93 A	930 A	139 A	1395 A
MCD5-1200C	120 A	1200 A	180 A	1800 A
MCD5-1410C	141 A	1410 A	211 A	2115 A
MCD5-1600C	160 A	1600 A	240 A	2400 A

4.12. Bypass Contactor

MCD 500 soft starters with model numbers MCD5-0021B ~ MCD5-0215B are internally bypassed and do not require an external bypass relay.

MCD 500 soft starters with model numbers MCD5-0245C ~ MCD5-1600C are not internally bypassed and may be installed with an external bypass relay. Select a relay with an AC1 rating greater than or equal to the full load current rating of the connected motor.

4.13. Main Contactor

A main contactor must be installed if the MCD 500 is connected to the motor in inside delta format and is optional for in-line connection. Select a contactor with an AC3 rating greater than or equal to the full load current rating of the connected motor.

4.14. Circuit Breaker

A shunt trip circuit breaker may be used instead of a main contactor to isolate the motor circuit in the event of a soft starter trip. The shunt trip mechanism must be powered from the supply side of the circuit breaker or from a separate control supply.

4.15. Power Factor Correction

If power factor correction is used, a dedicated contactor should be used to switch in the capacitors. Power factor correction capacitors must be connected to the input side of the soft starter. Connecting power factor correction capacitors to the output side will damage the soft starter.

4.16. Fuses

HRC fuses can be used for Type 1 coordination and semiconductor fuses can be used for Type 2 coordination and to reduce the risk of damage to SCRs from transient overload currents.



N.B.!:

Adaptive Acceleration Control (AAC) controls the motor's speed profile, within the programmed time limit. This may result in a higher level of current than traditional control methods.

For applications using Adaptive Acceleration Control to soft stop the motor with stop times greater than 30 seconds, motor branch protection should be selected as follows:

- standard HRC line fuses: minimum 150% motor full load current
- motor rated line fuses: minimum rating 100/150% motor full load current
- motor control circuit breaker minimum long time setting: 150% motor full load current,
- motor control circuit breaker minimum short time setting: 400% motor full load current for 30 seconds

Fuse recommendations are calculated for 40°C, up to 1000 m

For models marked — there is no suitable fuse.

4.16.2. Bussman Fuses - Square Body (170M)

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	170M1314	170M1314	170M1314
MCD5-0037B	8000	170M1316	170M1316	170M1316
MCD5-0043B	10500	170M1318	170M1318	170M1318
MCD5-0053B	15000	170M1318	170M1318	170M1318
MCD5-0068B	15000	170M1319	170M1319	170M1318
MCD5-0084B	51200	170M1321	170M1321	170M1319
MCD5-0089B	80000	170M1321	170M1321	170M1321
MCD5-0105B	125000	170M1321	170M1321	170M1321
MCD5-0131B	125000	170M1321	170M1321	170M1321
MCD5-0141B	320000	170M2621	170M2621	170M2621
MCD5-0195B	320000	170M2621	170M2621	170M2621
MCD5-0215B	320000	170M2621	170M2621	170M2621
MCD5-0245C	320000	170M2621	170M2621	170M2621
MCD5-0360C	238000	170M6010	170M6010	170M6010
MCD5-0380C	320000	170M6011	170M6011	—
MCD5-0428C	320000	170M6011	170M6011	—
MCD5-0595C	1200000	170M6015	170M6015	170M6014
MCD5-0619C	1200000	170M6015	170M6015	170M6014
MCD5-0790C	2530000	170M6017	170M6017	170M6016
MCD5-0927C	4500000	170M6019	170M6019	170M6019
MCD5-1200C	4500000	170M6021	—	—
MCD5-1410C	6480000	—	—	—
MCD5-1600C	12500000	—	—	—

4.16.3. Bussman Fuses - British Style (BS88)

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	63FE	63FE	63FE
MCD5-0037B	8000	120FEE	120FEE	120FEE

MCD5-0043B	10500	120FEE	120FEE	120FEE
MCD5-0053B	15000	200FEE	200FEE	200FEE
MCD5-0068B	15000	200FEE	200FEE	200FEE
MCD5-0084B	51200	200FEE	200FEE	200FEE
MCD5-0089B	80000	280FM	280FM	280FM
MCD5-0105B	125000	280FM	280FM	280FM
MCD5-0131B	125000	280FM	280FM	280FM
MCD5-0141B	320000	450FMM	450FMM	450FMM
MCD5-0195B	320000	450FMM	450FMM	450FMM
MCD5-0215B	320000	450FMM	450FMM	450FMM
MCD5-0245C	320000	450FMM	450FMM	450FMM
MCD5-0360C	238000	—	—	—
MCD5-0380C	320000	400FMM*	400FMM*	400FMM*
MCD5-0428C	320000	—	—	—
MCD5-0595C	1200000	630FMM*	630FMM*	—
MCD5-0619C	1200000	630FMM*	630FMM*	—
MCD5-0790C	2530000	—	—	—
MCD5-0927C	4500000	—	—	—
MCD5-1200C	4500000	—	—	—
MCD5-1410C	6480000	—	—	—
MCD5-1600C	12500000	—	—	—

* Two parallel connected fuses required per phase.

4.16.4. Ferraz Fuses - HSJ

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	HSJ40**	HSJ40**	Not suitable
MCD5-0037B	8000	HSJ80**	HSJ80**	
MCD5-0043B	10500	HSJ90**	HSJ90**	
MCD5-0053B	15000	HSJ110**	HSJ110**	
MCD5-0068B	15000	HSJ125**	HSJ125**	
MCD5-0084B	51200	HSJ175	HSJ175**	
MCD5-0089B	80000	HSJ175	HSJ175	
MCD5-0105B	125000	HSJ225	HSJ225	
MCD5-0131B	125000	HSJ250	HSJ250**	
MCD5-0141B	320000	HSJ300	HSJ300	
MCD5-0195B	320000	HSJ350	HSJ350	
MCD5-0215B	320000	HSJ400**	HSJ400**	
MCD5-0245C	320000	HSJ450**	HSJ450**	
MCD5-0360C	238000	Not suitable	Not suitable	
MCD5-0380C	320000			
MCD5-0428C	320000			
MCD5-0595C	1200000			
MCD5-0619C	1200000			
MCD5-0790C	2530000			
MCD5-0927C	4500000			
MCD5-1200C	4500000			
MCD5-1410C	6480000			
MCD5-1600C	12500000			

** Two series connected fuses required per phase.

4.16.5. Ferraz Fuses - North American Style (PSC 690)

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	A070URD30XXX0063	A070URD30XXX0063	—
MCD5-0037B	8000	A070URD30XXX0125	A070URD30XXX0125	A070URD30XXX0125
MCD5-0043B	10500	A070URD30XXX0125	A070URD30XXX0125	A070URD30XXX0125
MCD5-0053B	15000	A070URD30XXX0125	A070URD30XXX0125	A070URD30XXX0125
MCD5-0068B	15000	A070URD30XXX0160	A070URD30XXX0160	A070URD30XXX0160
MCD5-0084B	51200	A070URD30XXX0200	A070URD30XXX0200	A070URD30XXX0200
MCD5-0089B	80000	A070URD30XXX0200	A070URD30XXX0200	A070URD30XXX0200
MCD5-0105B	125000	A070URD30XXX0315	A070URD30XXX0315	A070URD30XXX0315
MCD5-0131B	125000	A070URD30XXX0315	A070URD30XXX0315	A070URD30XXX0315
MCD5-0141B	320000	A070URD30XXX0315	A070URD30XXX0315	A070URD30XXX0315
MCD5-0195B	320000	A070URD30XXX0450	A070URD30XXX0450	A070URD30XXX0450
MCD5-0215B	320000	A070URD30XXX0450	A070URD30XXX0450	A070URD30XXX0450
MCD5-0245C	320000	A070URD30XXX0450	A070URD30XXX0450	A070URD30XXX0450
MCD5-0360C	238000	A070URD33XXX0630	A070URD33XXX0630	A070URD33XXX0630
MCD5-0380C	320000	A070URD33XXX0700	A070URD33XXX0700	—
MCD5-0428C	320000	A070URD33XXX0700	A070URD33XXX0700	—
MCD5-0595C	1200000	A070URD33XXX1000	A070URD33XXX1000	A070URD33XXX1000
MCD5-0619C	1200000	A070URD33XXX1000	A070URD33XXX1000	A070URD33XXX1000
MCD5-0790C	2530000	A070URD33XXX1400	A070URD33XXX1400	A070URD33XXX1400
MCD5-0927C	4500000	A070URD33XXX1400	A070URD33XXX1400	A070URD33XXX1400
MCD5-1200C	4500000	A055URD33XXX2250	—	—
MCD5-1410C	6480000	A055URD33XXX2250	—	—
MCD5-1600C	12500000	—	—	—

XXX = blade type. Refer to Ferraz catalog for details.

4.16.6. Ferraz Fuses - European Style (PSC 690)

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	6.9URD30D11A0050	6.9URD30D11A0050	6.9URD30D11A0050
MCD5-0037B	8000	6.9URD30D11A0125	6.9URD30D11A0125	6.9URD30D11A0125
MCD5-0043B	10500	6.9URD30D11A0125	6.9URD30D11A0125	6.9URD30D11A0125
MCD5-0053B	15000	6.9URD30D11A0125	6.9URD30D11A0125	6.9URD30D11A0125
MCD5-0068B	15000	6.9URD30D11A0160	6.9URD30D11A0160	6.9URD30D11A0160
MCD5-0084B	51200	6.9URD30D11A0200	6.9URD30D11A0200	6.9URD30D11A0200
MCD5-0089B	80000	6.9URD30D11A0200	6.9URD30D11A0200	6.9URD30D11A0200
MCD5-0105B	125000	6.9URD30D11A0315	6.9URD30D11A0315	6.9URD30D11A0315
MCD5-0131B	125000	6.9URD30D11A0315	6.9URD30D11A0315	6.9URD30D11A0315
MCD5-0141B	320000	6.9URD30D11A0315	6.9URD30D11A0315	6.9URD30D11A0315
MCD5-0195B	320000	6.9URD31D11A0450	6.9URD31D11A0450	6.9URD31D11A0450
MCD5-0215B	320000	6.9URD31D11A0450	6.9URD31D11A0450	6.9URD31D11A0450
MCD5-0245C	320000	6.9URD31D11A0450	6.9URD31D11A0450	6.9URD31D11A0450
MCD5-0360C	238000	6.9URD33D11A0630	6.9URD33D11A0630	6.9URD33D11A0630
MCD5-0380C	320000	6.9URD33D11A0800	6.9URD33D11A0800	6.9URD33D11A0800
MCD5-0428C	320000	6.9URD33D11A0800	6.9URD33D11A0800	6.9URD33D11A0800
MCD5-0595C	1200000	6.9URD33D11A1000	6.9URD33D11A1000	6.9URD33D11A1000
MCD5-0619C	1200000	6.9URD33D11A1000	6.9URD33D11A1000	6.9URD33D11A1000
MCD5-0790C	2530000	6.6URD33D11A1400	6.6URD33D11A1400	—

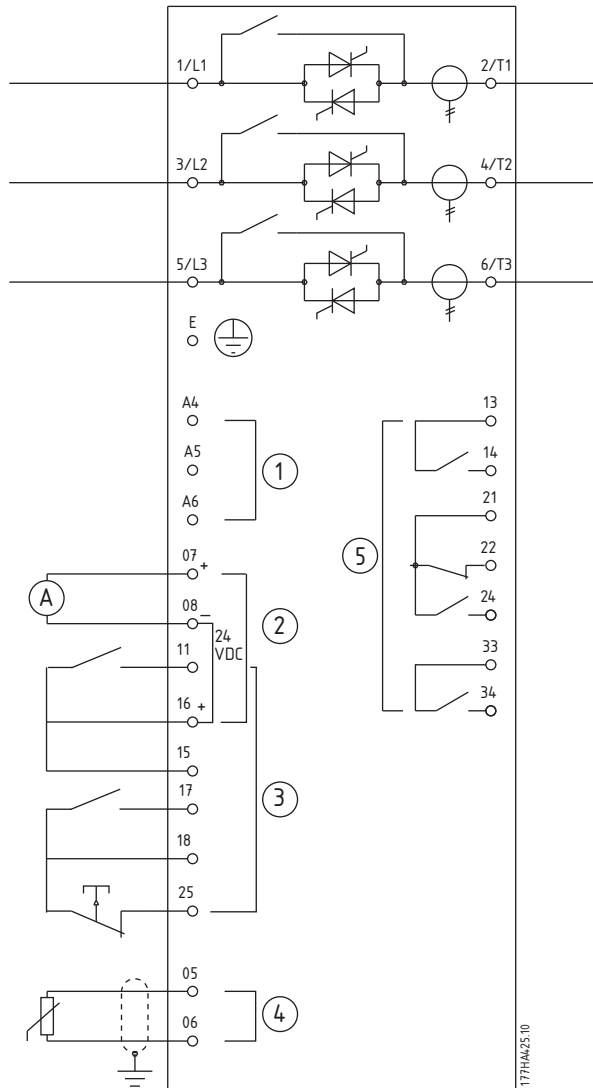
MCD5-0927C	4500000	6.6URD33D11A1400	6.6URD33D11A1400	—
MCD5-1200C	4500000	6.9URD233PLAF2200	6.9URD233PLAF2200	—
MCD5-1410C	6480000	6.9URD233PLAF2200	6.9URD233PLAF2200	6.9URD233PLAF2200
MCD5-1600C	12500000	—	—	—

4.16.7. Ferraz Fuses - AJT

Model	SCR I ² t (A ² s)	Supply Voltage ≤ 440 VAC	Supply Voltage ≤ 575 VAC	Supply Voltage ≤ 690 VAC
MCD5-0021B	1150	AJT25	AJT25	Not suitable
MCD5-0037B	8000	AJT50	AJT50	
MCD5-0043B	10500	AJT50	AJT50	
MCD5-0053B	15000	AJT60	AJT60	
MCD5-0068B	15000	AJT80	AJT80	
MCD5-0084B	51200	AJT100	AJT100	
MCD5-0089B	80000	AJT100	AJT100	
MCD5-0105B	125000	AJT125	AJT125	
MCD5-0131B	125000	AJT150	AJT150	
MCD5-0141B	320000	AJT175	AJT175	
MCD5-0195B	320000	AJT200	AJT200	
MCD5-0215B	320000	AJT250	AJT250	
MCD5-0245C	320000	AJT300	AJT300	
MCD5-0360C	238000	AJT400	AJT400	
MCD5-0380C	320000	AJT450	AJT450	
MCD5-0428C	320000	AJT450	AJT450	
MCD5-0595C	1200000	—	—	
MCD5-0619C	1200000	—	—	
MCD5-0790C	2530000	—	—	
MCD5-0927C	4500000	A4BQ1200	A4BQ1200	
MCD5-1200C	4500000	—	—	
MCD5-1410C	6480000	—	—	
MCD5-1600C	12500000	A4BQ2500	A4BQ2500	

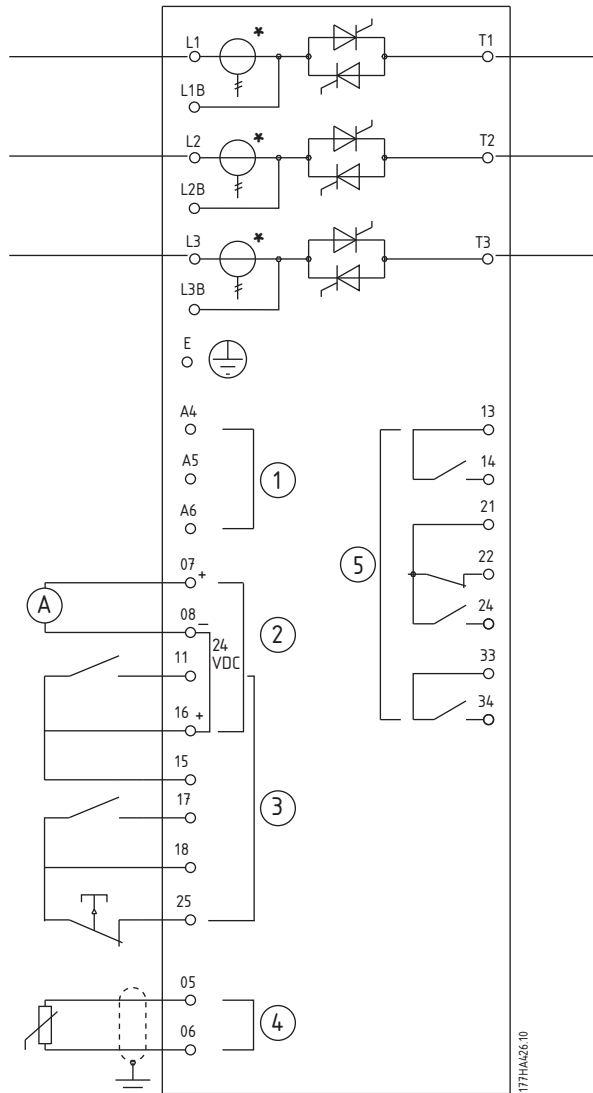
4.17. Schematic Diagrams

4.17.1. Internally bypassed models



1	Control supply (model dependent)
2	Outputs
07, 08	Programmable analog output
16, 08	24 VDC output
3	Remote control inputs
11, 15, 16	Input A
17, 18	Start/Stop
25, 18	Reset
4	Motor thermistor input (PTC only)
5	Relay outputs
13, 14	Relay output A
21, 22, 24	Relay output B
33, 34	Relay output C

4.17.2. Non-bypassed models



1	Control supply (model dependent)
2	Outputs
07, 08	Programmable analog output
16, 08	24 VDC output
3	Remote control inputs
11, 15, 16	Programmable input
17, 18	Start/Stop
25, 18	Reset
4	Motor thermistor input (PTC only)
5	Relay outputs
13, 14	Relay output A
21, 22, 24	Relay output B
33, 34	Relay output C



NB!:

* MCD5-0245C current transformers are located on the output. Bypass terminals are labelled T1B, T2B and T3B.

5. Application Examples

5.1. Motor Overload Protection

Motor overload protection in the MCD 500 uses a second order thermal model. This calculates the motor temperature based on the thermal properties of two components:

- Motor Body – This has a large thermal capacity and affects the long term behaviour of the motor.
- Motor windings – These have a low thermal capacity and affects the short term thermal behaviour of the motor.

The thermal model also takes into account the influence of motor current, iron losses, winding resistance losses, and different cooling rates during run and at standstill.

The value displayed on the LCP is the value for the winding model as a percentage of the rated capacity of the motor.

The MCD 500 calculates the motor's thermal capacity based on the settings in *Primary Motor Set*. Par. 1-1 *Motor FLC* should be set to the motor's rated FLC. Do not add the overload rating as this is computed by the MCD 500.

5.2. AAC Adaptive Acceleration Control

AAC Adaptive Acceleration Control is a new form of motor control based on the motor's own performance characteristics. With AAC, the user selects the starting or stopping profile that best matches the load type and the starter automatically controls the motor to match the profile. The MCD 500 offers three profiles - early, constant and late acceleration and deceleration.

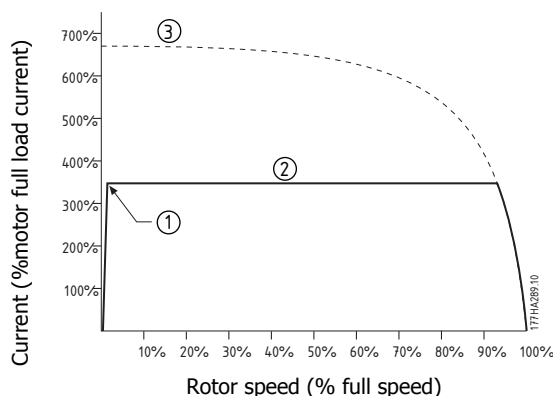
AAC uses two algorithms, one to measure the motor's characteristics and one to control the motor. The MCD 500 uses the first start to determine the motor's characteristics at zero speed and at maximum speed. During each subsequent start and stop, the starter dynamically adjusts its control to ensure the motor's actual performance matches the selected profile throughout the start. The starter increases power to the motor if the actual speed is too low for the profile, or decreases power if the speed is too high.

5.3. Starting Modes

5.3.1. Constant Current

Constant current is the traditional form of soft starting, which raises the current from zero to a specified level and keeps the current stable at that level until the motor has accelerated.

Constant current starting is ideal for applications where the start current must be kept below a particular level.



1: Initial current (Par. 1-5)

2: Current limit (Par. 1-4)

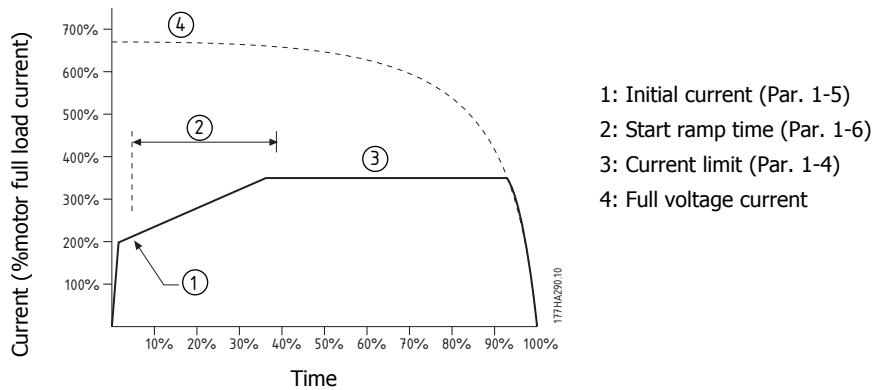
3: Full voltage current

5.3.2. Current Ramp

Current ramp soft starting raises the current from a specified starting level (1) to a maximum limit (3), over an extended period of time (2).

Current ramp starting can be useful for applications where:

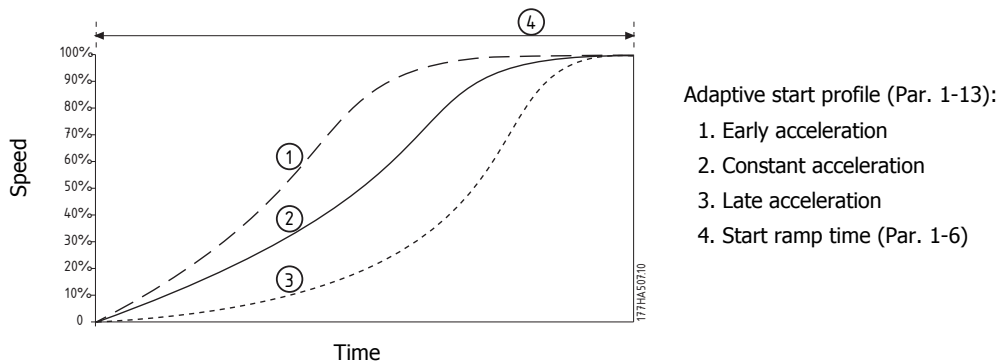
- the load can vary between starts (for example a conveyor which may start loaded or unloaded). Set the initial current (Par. 1-5) to a level that will start the motor with a light load, and the current limit (Par. 1-4) to a level that will start the motor with a heavy load.
- the load breaks away easily, but starting time needs to be extended (for example a centrifugal pump where pipeline pressure needs to build up slowly).
- the electricity supply is limited (for example a generator set), and a slower application of load will allow greater time for the supply to respond.



5.3.3. AAC Adaptive Acceleration Control

To use AAC Adaptive Acceleration Control to control starting performance:

1. Select Adaptive Control from the Start Mode menu (Par. 1-3)
2. Set the desired Start Ramp Time (Par. 1-6)
3. Select the desired Adaptive Start Profile (Par. 1-13)
4. Set a start Current Limit (Par. 1-4) sufficiently high to allow a successful start. The first AAC start will be a Constant Current start. This allows the MCD 500 to learn the characteristics of the connected motor. This motor data is used by the MCD 500 during subsequent AAC Adaptive Acceleration Control starts.



NB!:

AAC will control the load according to the programmed profile. Start current will vary according to the selected acceleration profile and start time.

AAC cannot start the motor faster than a direct on-line (DOL) start.

If replacing a motor connected to an MCD 500 programmed for AAC starting, or if the the starter has been tested on a different motor prior to actual installation, the starter will need to learn the characteristics of the new motor. To force the MCD 500 into learn mode, adjust parameter 1-12 Adaptive Control Gain as follows:

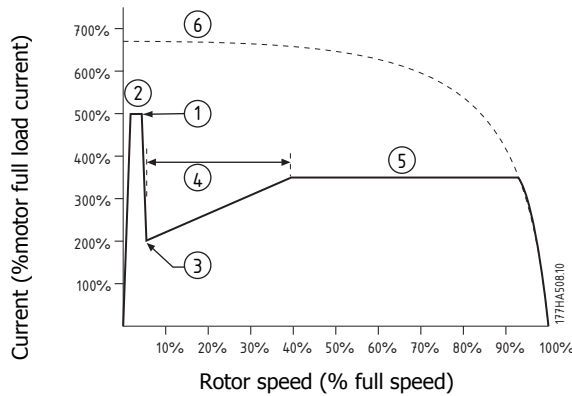
If 1-12 is at default setting of 75%, adjust to 76%.

If 1-12 is not at default setting of 75%, adjust to 75%.

5.3.4. Kickstart

Kickstart provides a short boost of extra torque at the beginning of a start, and can be used in conjunction with current ramp or constant current starting.

Kickstart can be useful to help start loads that require high breakaway torque but then accelerate easily (for example flywheel loads such as presses).



- 1: Kickstart level (Par. 1-7)
- 2: Kickstart time (Par. 1-8)
- 3: Initial current (Par. 1-5)
- 4: Start ramp time (Par. 1-6)
- 5: Current limit (Par. 1-4)
- 6: Full voltage current

5.4. Stopping Modes

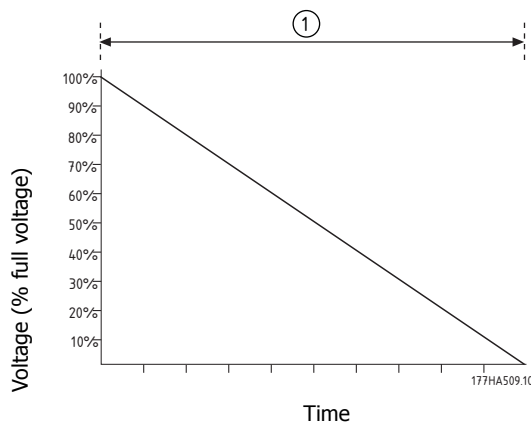
5.4.1. Coast to Stop

Coast to stop lets the motor slow at its natural rate, with no control from the soft starter. The time required to stop will depend on the type of load.

5.4.2. TVR Soft Stop

Timed voltage ramp reduces the voltage to the motor gradually over a defined time. The load may continue to run after the stop ramp is complete.

Timed voltage ramp stopping can be useful for applications where the stop time needs to be extended, or to avoid transients on generator set supplies.

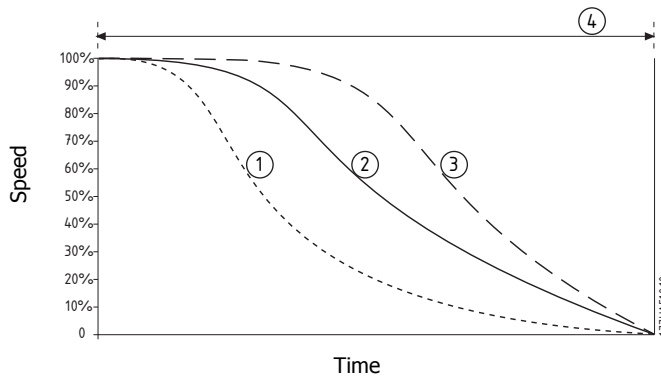


- 1: Stop time (Par. 1-11)

5.4.3. AAC Adaptive Acceleration Control

To use AAC Adaptive Acceleration Control to control stopping performance:

1. Select Adaptive Control from the Stop Mode menu (Par. 1-10)
2. Set the desired Stop Time (Par. 1-11)
3. Select the required Adaptive Stop Profile (Par. 1-14)



AAC Adaptive stop profile (Par. 1-14):

1. Early deceleration
2. Constant deceleration
3. Late deceleration
4. Stop time (Par. 1-11)

5.4.4. Brake



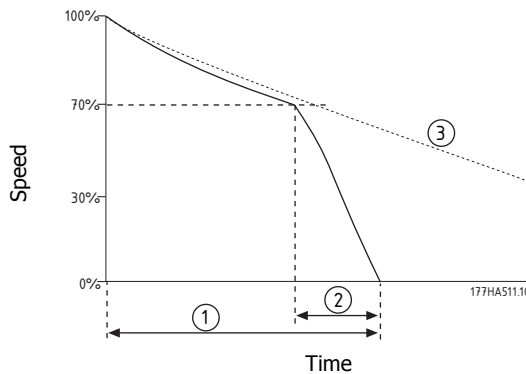
NB!:

If the brake torque is set too high, the motor will stop before the end of the brake time and the motor will suffer unnecessary heating which could result in damage.

When brake is selected, the MCD 500 uses DC injection to slow the motor.

MCD 500 braking:

- Does not require the use of a DC brake contactor
- Controls all three phases so that the braking currents and associated heating is evenly distributed through the motor.



- 1: Stop time (Par. 1-11)
- 2: Brake time (Par. 1-16)
- 3: Coast to stop time (without braking)

Braking has two stages:

1. Pre-brake: provides an intermediate level of braking to slow motor speed to a point where full brake can be operated successfully (approximately 70% speed).
2. Full brake: brake provides maximum braking torque but is ineffective at speeds greater than approximately 70%.

To configure the MCD 500 for brake operation:

1. Set Par. 1-11 for the desired stopping time duration (1). This is the total braking time and must be set sufficiently longer than the brake time (Par. 1-16) to allow the pre-braking stage to reduce motor speed to approximately 70%. If the stop time is too short, braking will not be successful and the motor will coast to stop.

2. Set Brake Time (Par. 1-16) to approximately one quarter of the programmed Stop Time. This sets the time for the Full Brake stage (2).

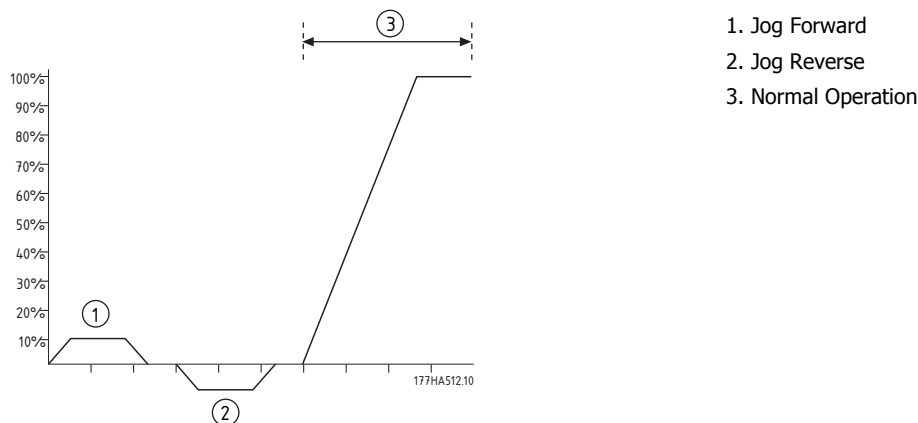
3. Adjust the Brake Torque (Par. 1-15) so that the desired stopping performance is achieved. If set too low, the motor will not stop completely and will coast to stop by the end of the braking period.

Contact your local supplier for further information for installations using an external zero-speed sensor (e.g. applications with variable load during the braking cycle).

5.5. Jog Operation

Jog runs the motor at reduced speed (approximately 11% of full running speed), to allow alignment of the load or to assist servicing. The motor can be jogged in either forward or reverse direction.

In some applications the available jog torque may not be sufficient to accelerate the motor as required. In these applications a customised forward jog profile can be programmed using the parameters in parameter group 7. Contact your local distributor for more information.



To activate jog operation, use a programmable input (Par. 3-3). If any other command is received when jogging the starter will stop and await a new command.



NB!:

Jog is only available for the primary motor. Soft start and soft stop are not available during jog operation.

5.6. Inside Delta Operation

AAC, Jog and Brake functions are not supported in inside delta (six-wire) operation. If these functions are programmed when the starter is connected inside delta the behaviour is as given below:

AAC Start	The starter performs a Constant Current Start.
AAC Stop	The starter performs a TVR Soft Stop if Stop Time is >0 secs. If Stop Time is set to 0 secs the starter performs a Coast to Stop.
Jog	The starter issues a warning with the error message Unsupported Option.
Brake	The starter performs a Coast to Stop.



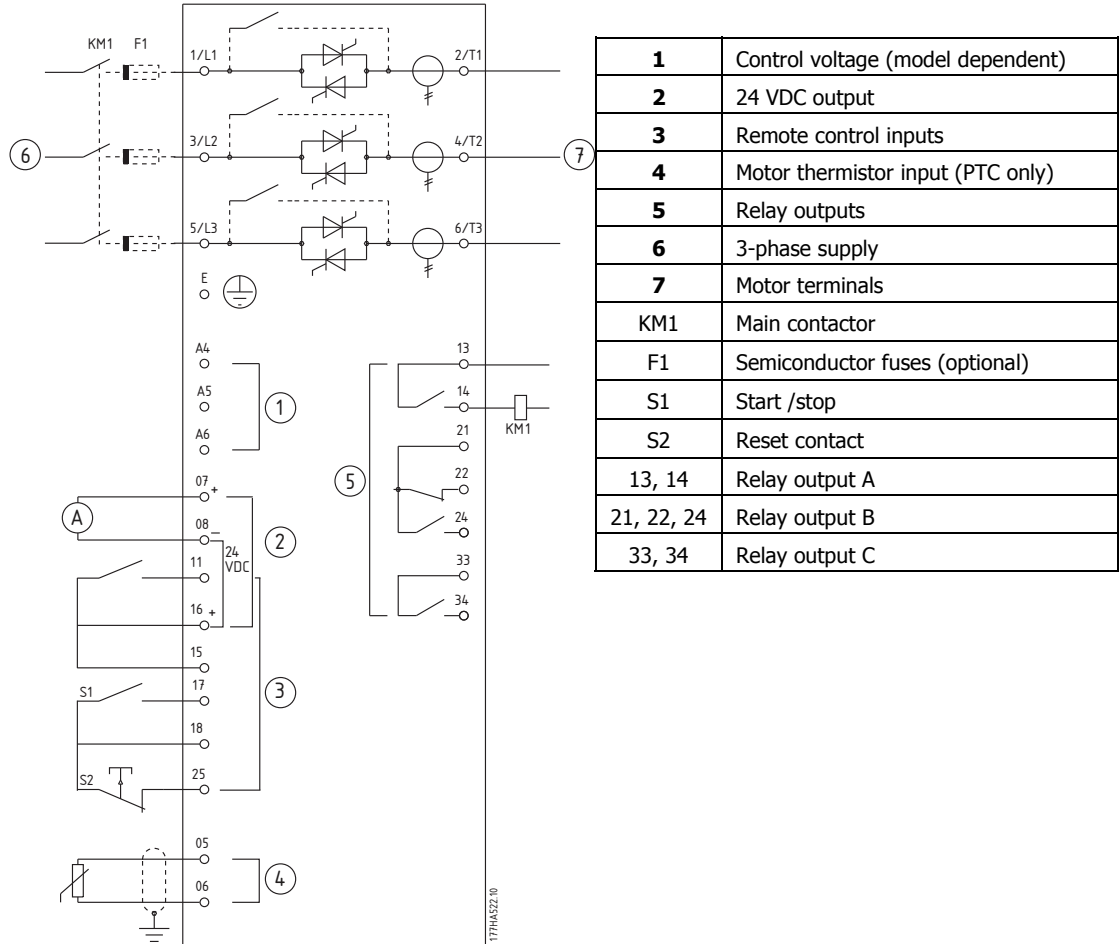
NB!:

When connected in inside delta, current imbalance is the only phase loss protection that is active during run. Do not disable current imbalance protection during inside delta operation.

5.7. Installation with Main Contactor

The MCD 500 is installed with a main contactor (AC3 rated). Control voltage must be supplied from the input side of the contactor.

The main contactor is controlled by the MCD 500 Main Contactor output, which by default is assigned to Output Relay A (terminals 13, 14).



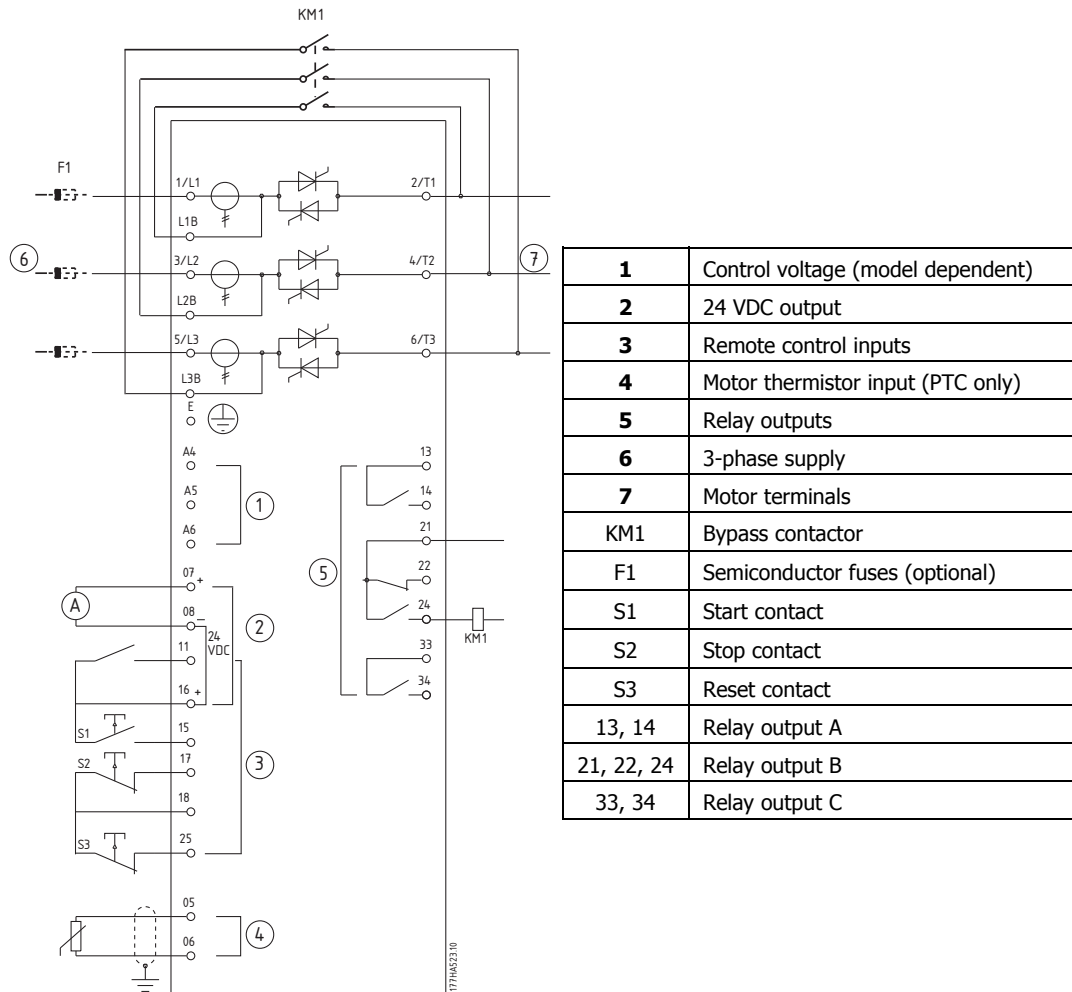
Parameter settings:

- **Parameter 4-1 Relay A Function**

- Select Main Contactor - assigns the Main Contactor function to Relay Output A (default value).

5.8. Installation with Bypass Contactor

The MCD 500 is installed with a bypass relay (AC1 rated). The bypass relay is controlled by the MCD 500 Run Output which by default is assigned to Output Relay B (terminals 21, 22, 24).



Parameter settings:

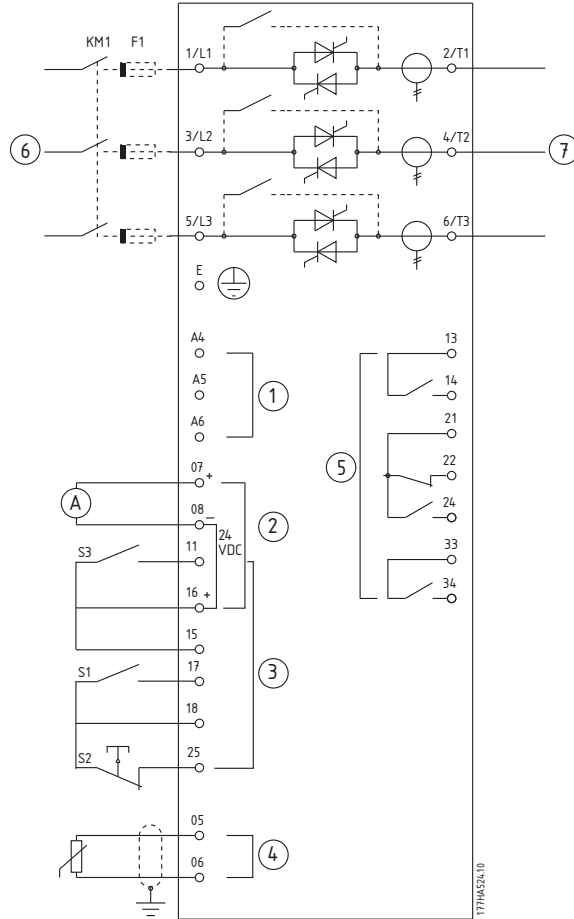
■ **Parameter 4-4 Relay B Function**

- Select Run - assigns the run output function to Relay Output B (default value).

5.9. Emergency Run Operation

In normal operation the MCD 500 is controlled via a remote two wire signal (terminals 17, 18).

Emergency Run is controlled by a two wire circuit connected to Input A (terminals 11, 16). Closing Input A causes the MCD 500 to run the motor and ignore all trip conditions.



1	Control voltage (model dependent)
2	24 VDC output
3	Remote control inputs
4	Motor thermistor input (PTC only)
5	Relay outputs
6	3-phase supply
7	Motor terminals
S1	Start/stop contact
S2	Reset contact
S3	Emergency Run contact
13, 14	Relay output A
21, 22, 24	Relay output B
33, 34	Relay output C

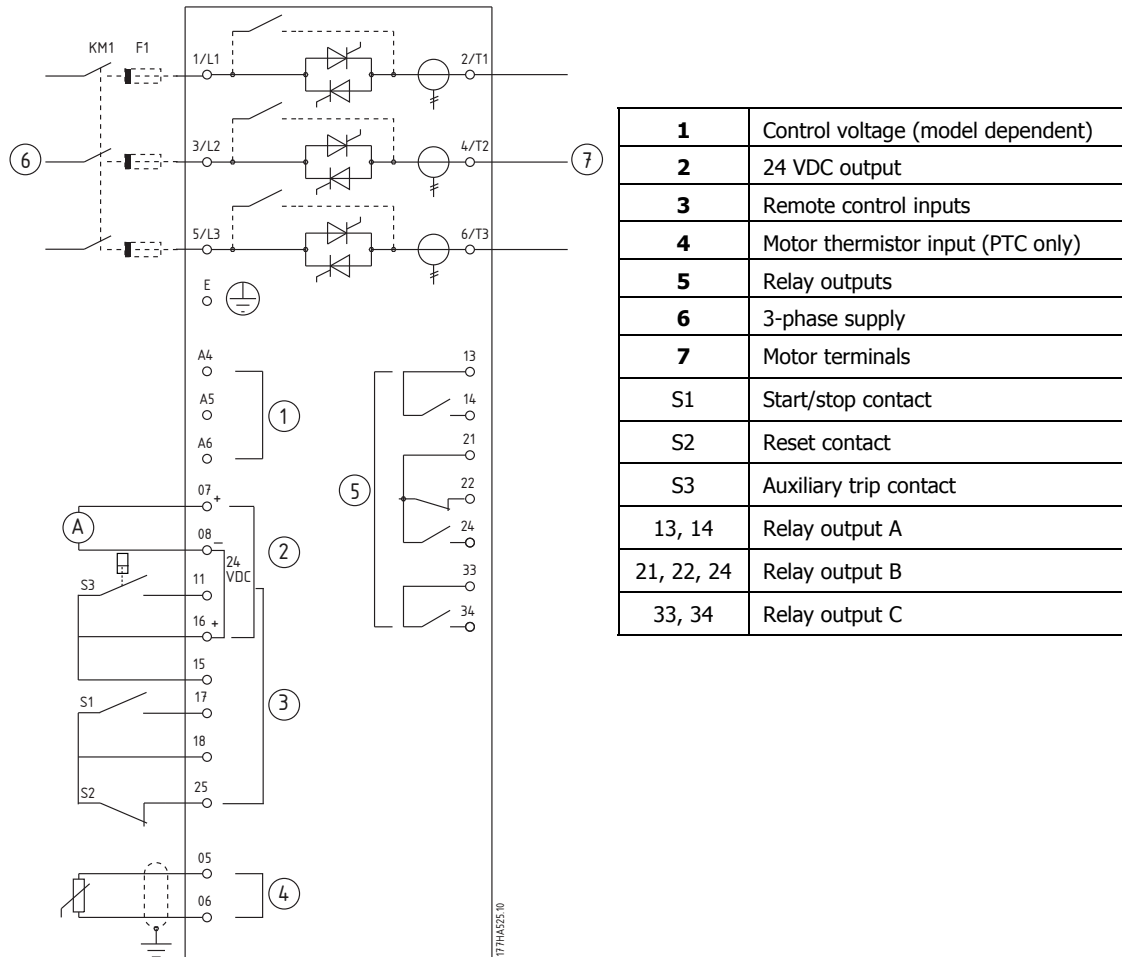
Parameter settings:

- Par. 3-3 *Input A Function*
 - Select Emergency Run - assigns Input A to Emergency Run function.
- Par. 15-3 (*Emergency Run*)
 - Select Enable - Enables the Emergency Run mode

5.10. Auxiliary Trip Circuit

In normal operation the MCD 500 is controlled via a remote two wire signal (terminals 17, 18).

Input A (terminals 11, 16) is connected to an external trip circuit (such as a low pressure alarm switch for a pumping system). When the external circuit activates, the soft starter trips, which stops the motor.



Parameter settings:

- Par. 3-3 *Input A Function*
 - Select Input Trip (N/O) assigns the Input A to Auxiliary Trip (N/O) function
- Par. 3-4 *Input A Name*
 - Select a name e.g. Low Pressure - assigns a name to Input A.
- Par. 3-8 *Remote Reset Logic*
 - Select as required e.g. Normally Closed - the input behaves like a normally closed contact.

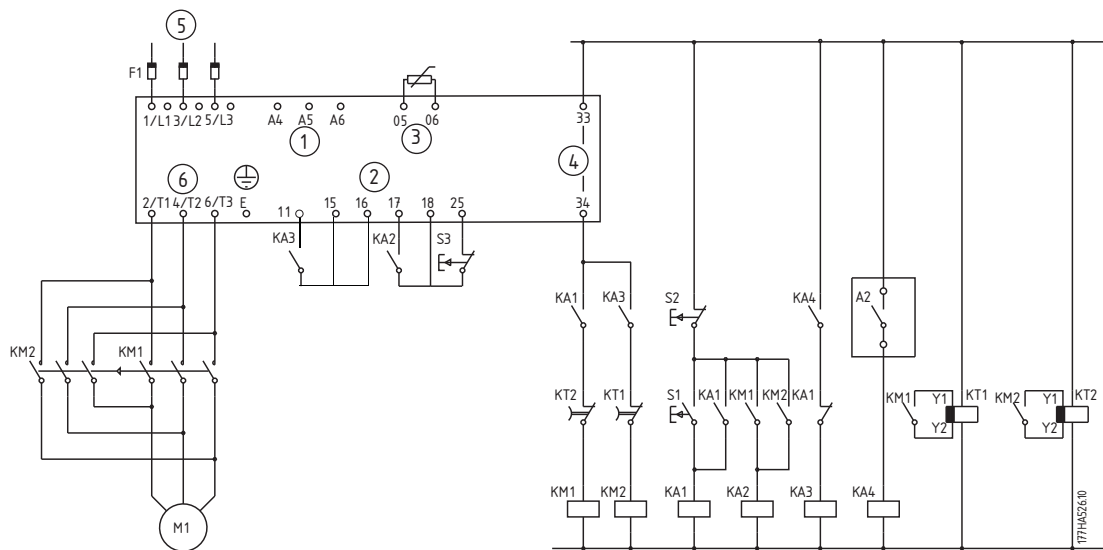
5.11. Soft Braking

For high inertia loads the MCD 500 can be configured for soft braking.

In this application the MCD 500 is employed with forward run and braking contactors. When MCD 500 receives a start signal (button S1), it closes the forward run contactor (KM1) and controls the motor according to the programmed primary motor settings.

When the MCD 500 receives a stop signal (button S2), it opens the forward run contactor (KM1) and closes the braking contactor (KM2) after a delay of approximately 2-3 seconds (KT1). KA3 is also closed to activate the secondary motor settings, which should be user programmed for the desired stopping performance characteristics.

When motor speed approaches zero, the external shaft rotation sensor (A2) stops the soft starter and opens the braking contactor (KM2).



1	Control voltage (model dependent)
2	Remote control inputs
3	Motor thermistor input (PTC only)
4	Relay outputs
5	3-phase supply
6	Motor terminals

A2	Shaft rotation sensor
KA1	Run relay
KA2	Start relay
KA3	Brake relay
KA4	Rotation sensing relay
KM1	Line contactor (Run)
KM2	Line contactor (Brake)
KT1	Run delay timer
KT2	Brake delay timer
S1	Start contact
S2	Stop contact
S3	Reset contact

Parameter settings:

■ Par. 3-3 *Input A Function*

- Select Motor Set Select - assigns Input A for Motor set selection.
- Set starting performance characteristics using the primary motor set (parameter group 1).
- Set braking performance characteristics using the secondary motor settings (parameter group 7).

■ Par. 4-7 *Relay C Function*

- Select Trip - assigns Trip function to Relay Output C.

**NB!:**

If the MCD 500 trips on supply frequency (Par. 16-5 *Frequency*) when the braking contactor KM2 opens, modify the setting of Pars. 2-8 ~ 2-10.

5.12. Two Speed Motor

The MCD 500 can be configured for control of dual speed Dahlander type motors, using a high speed contactor (KM1), low speed contactor (KM2) and a star contactor (KM3).

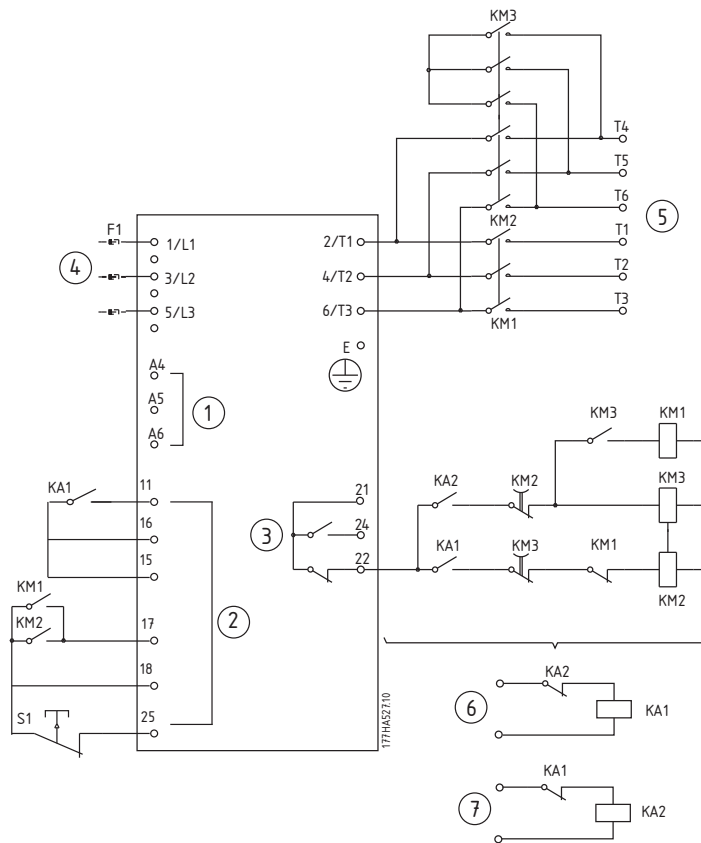


NB!:

Pole Amplitude Modulated (PAM) motors alter the speed by effectively changing the stator frequency using external winding configuration. Soft starters are not suitable for use with this type of two-speed motor.

When the soft starter receives a high speed start signal, it closes the high speed contactor (KM1) and star contactor (KM3), then controls the motor according to the primary motor settings (Pars. 1-1 ~ 1-16).

When the soft starter receives a low speed start signal, it closes the low speed contactor (KM2). This closes Input A and the MCD 500 controls the motor according to the secondary motor settings (Pars. 7-1 ~ 7-16).



1	Control voltage
2	Remote control inputs
3	Relay outputs
4	3-phase supply
5	Motor terminals
6	Remote low-speed start input
7	Remote high-speed start input

KA1	Remote start relay (low speed)
KA2	Remote start relay (high speed)
KM1	Line contactor (high speed)
KM2	Line contactor (low speed)
KM3	Star contactor (high speed)
S1	Reset contact
21, 22, 24	Relay output B



Contactors KM2 and KM3 must be mechanically interlocked.

Parameter settings:

- Par. 3-3 *Input A Function*
 - Select Motor Set Select - assigns Input A for Motor set selection.
 - Set high speed performance characteristics using Pars. 1-1 ~ 2-9.
 - Set low speed performance characteristics using Pars. 7-1 ~ 7-16.
- Par. 4-4 *Relay B Function*
 - Select Trip - assigns Trip function to Relay Output B

**NB!:**

If the MCD 500 trips on supply frequency (Par. 16-5 *Frequency*) when the high-speed start signal (7) is removed, modify the setting of Pars. 2-8 ~ 2-10.

6. Operation

In Hand On mode:

- To soft start the motor, press the **HAND ON** button on the LCP.
- To stop the motor, press the **OFF** button on the LCP.
- To reset a trip on the starter, press the **RESET** button on the LCP.
- To emergency stop the motor, press the local **OFF** and **RESET** buttons at the same time. The soft starter will remove power from the motor and open the main contactor, and the motor will coast to stop. Emergency stop can also be controlled via a programmable input.

In Auto On mode:

- To soft start the motor, activate the Start remote input.
- To stop the motor, activate the Stop remote input.
- To reset a trip on the starter, activate the Reset remote input.



NB!:

Brake and Jog functions operate only with in-line connected motors (=> Inside Delta Operation)

6.2. The LCP

1	Four-line display for status and programming details.
2	Display control buttons: STATUS: Return to the status displays QUICK MENU: Open the Quick Menu MAIN MENU: Open the Main Menu ALARM LOG: Open the Alarm Log
3	Menu navigation buttons: BACK: Exit the menu or parameter, or cancel a parameter change OK: Enter a menu or parameter, or save a parameter change ▲ ▼: Scroll to the next or previous menu or parameter, change the setting of the current parameter or scroll through the status screens.
4	Soft starter local control buttons: HAND ON: Start the motor and enter Hand On mode. OFF: Stop the motor. AUTO ON: Set the starter to Auto On mode. RESET: Reset a trip (Hand On mode only).
5	Remote input status LEDs.

6.3. Local Control Buttons

If Par. 3-1 is set to LCL/RMT Anytime or LCL/RMT When OFF the HAND ON and AUTO ON buttons are always active. If the MCD 500 is in Auto On mode, pressing the HAND ON button will enter Hand On mode and start the motor.

If Par. 3-1 is set to Remote Control Only, the OFF button is disabled and the motor must be stopped by remote control or via the serial communication network.

6.4. Displays

The LCP displays a wide range of performance information about the soft starter. Press the **STATUS** button to access the status display screens, then use the **▲** and **▼** buttons to select the information

to display. To return to the status screens from within a menu, press the **BACK** button repeatedly or press the **STATUS** button to return to S1 screen.

- Temperature monitoring
- Programmable screen (=> parameters 8-2~8-5)
- Current
- Frequency
- Motor power
- Last start information
- Date and time
- SCR Conduction bar-graph



NB!:

Screens shown here are with the default settings.

6.4.1. Temperature Monitoring Screen (S1)

The temperature screen shows the temperature of the motor as a percentage of total thermal capacity, and also shows which motor data set is in use.

The temperature monitoring screen is the default status screen.

Ready	S1
MS1	000.0A 0000.0kW
	Primary Motor Set
M1	000%

6.4.2. Programmable Screen (S2)

The MCD 500's user-programmable screen can be configured to show the most important information for the particular application. Use parameters 8-2 to 8-5 to select which information to display.

Ready	S2
MS1	000.0A 0000.0kW
	-. pf
	00000 hrs

6.4.3. Average Current (S3)

The average current screen shows the average current of all three phases.

Ready	S3
MS1	000.0A 0000.0kW
	0.0A

6.4.4. Current Monitoring Screen (S4)

The current screen shows real-time line current on each phase.

Ready	S4
MS1	000.0A 0000.0kW
	Phase currents
	000.0A 000.0A 000.0A

6.4.5. Frequency Monitoring Screen (S5)

The frequency screen shows the mains frequency as measured by the soft starter.

Ready	S5
MS1	000.0A 0000.0kW
	00.0Hz

6.4.6. Motor Power Screen (S6)

The motor power screen shows motor power (kW, HP and kVA) and power factor.

Ready			S6
MS1	000.0A	0000.0kw	
	0000.0kW		0000HP
	0000kVA		-. - - pf

6.4.7. Last Start Information (S7)

The last start information screen shows details of the most recent successful start:

- start duration (seconds)
- maximum start current drawn (as a percentage of motor full load current)
- calculated rise in motor temperature

Ready			S7
MS1	000.0A	0000.0kw	
Last start			000 s
000 % FLC		Δ Temp	0%

6.4.8. Date and Time (S8)

The date/time screen shows the current system date and time (24 hour format). For details on setting the date and time, => *Set Date and Time*.

Ready			S8
MS1	000.0A	0000.0kw	
	YYYY MMM DD		
	HH:MM:SS		

6.4.9. SCR Conduction Bargraph

The SCR conduction bargraph shows the level of conduction on each phase.



7. Programming

You can access the menus at any time, including while the soft starter is running. All changes take effect immediately.

7.1. Access Control

Critical parameters (parameter group 15 and higher) are protected by a four-digit security access code, preventing unauthorised users from viewing or modifying parameter settings.

When a user attempts to enter a restricted parameter group, the LCP prompts for an access code. The access code is requested once for the programming session, and authorisation continues until the user closes the menu.

To enter the access code, use the **BACK** and **OK** buttons to select a digit, and the **▲** and **▼** buttons to change the value. When all four digits match your access code, press **OK**. The LCP will display an acknowledgement message before continuing.

Enter Access Code ****	OK
Access Allowed SUPERVISOR	

To change the access code, use Par. 15-1.



NB!:

The simulation tools and counter resets are also protected by the security access code.

The default access code is 0000.

You can lock the menus to prevent users from altering parameter settings. The adjustment lock can be set to allow Read & Write, Read Only or No Access using Par. 15-2.

If a user attempts to change a parameter value or access the Main Menu when the adjustment lock is active, an error message is displayed:

Access Denied Adj Lock is On

7.2. Quick Menu

The Quick Menu button provides access to menus for setting up the MCD 500 for simple applications.

7.2.1. Quick Setup

Quick setup provides access to commonly used parameters, allowing the user to configure the MCD 500 as required for the application. For details of individual parameters, => *Parameter Descriptions*.

1	Primary Mtr Set
1-1	Motor FLC
1-3	Start Mode
1-4	Current Limit
1-5	Initial Current
1-6	Start Ramp Time
1-9	Excess Start Time
1-10	Stop Mode
1-11	Stop Time
2	Protection
2-1	Phase Sequence
2-4	Undercurrent
2-5	Undercurrent Dly
2-6	Inst Overcurrent
2-7	Inst Overcurrent Dly
3	Inputs
3-3	Input A Function
3-4	Input A Name
3-5	Input A Trip
3-6	Input A Trip Dly
3-7	Input A Initial Dly
4	Outputs
4-1	Relay A Function
4-2	Relay A On Delay
4-3	Relay A Off Delay
4-4	Relay B Function
4-5	Relay B On Delay
4-6	Relay B Off Delay
4-7	Relay C Function
4-8	Relay C On Delay
4-9	Relay C Off Delay
4-10	Low Current Flag
4-11	High Current Flag
4-12	Motor Temp Flag
5	Start/Stop Timers
5-1	Auto-Start Type
5-2	Auto-Start Time
5-3	Auto-Stop Type
5-4	Auto-Stop Time
8	Display
8-1	Language
8-2	User Scrn Top L
8-3	User Scrn Top R
8-4	User Scrn Btm L
8-5	User Scrn Btm R

7.2.2. Application Setups

The application setups menu makes it easy to configure the MCD 500 for common applications. The MCD 500 selects the parameters relevant to the application and suggests a typical setting, and you can adjust each parameter to suit your exact requirements.

On the display the highlighted values are suggested values and the values indicated by a ► are the loaded values.

Always set parameter 1-1 *Motor FLC* to match the motor's nameplate full load current. The suggested value for motor FLC is the starter's minimum FLC.

Pump Centrifugal		Suggested Value
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Early Acceleration
Start Ramp Time		5 seconds
Current Limit		350%
Stop Mode		Adaptive Control
Adaptv Stop Profile		Late Deceleration
Stop Time		15 seconds
Pump Submersible		
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Early Acceleration
Start Ramp Time		5 seconds
Current Limit		350%
Stop Mode		Adaptive Control
Adaptv Stop Profile		Late Deceleration
Stop Time		5 seconds
Fan Damped		
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Constant Acceleration
Start Ramp Time		15 seconds
Current Limit		350%
Fan Undamped		
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Constant Acceleration
Start Ramp Time		20 seconds
Current Limit		400%
Excess Start Time		30 seconds
Locked Rotor Time		20 seconds
Compressor Screw		
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Constant Acceleration
Start Ramp Time		10 seconds
Current Limit		400%
Compressor Recip		
Motor FLC		
Start Mode		Adaptive Control
Adaptv Start Profile		Constant Acceleration
Start Ramp Time		10 seconds

Current Limit	450%
Conveyor	
Motor FLC	
Start Mode	Adaptive Control
Adaptv Start Profile	Late Acceleration
Start Ramp Time	15 seconds
Current Limit	400%
Stop Mode	Adaptive Control
Adaptv Stop Profile	Constant Deceleration
Stop Time	5 seconds
Crusher Rotary	
Motor FLC	
Start Mode	Adaptive Control
Adaptv Start Profile	Constant Acceleration
Start Ramp Time	20 seconds
Current Limit	400%
Excess Start Time	30 seconds
Locked Rotor Time	20 seconds
Crusher Jaw	
Motor FLC	
Start Mode	Adaptive Control
Adaptv Start Profile	Constant Acceleration
Start Ramp Time	30 seconds
Current Limit	450%
Excess Start Time	40 seconds
Locked Rotor Time	30 seconds

7.2.3. Loggings

The Loggings menu allows the user to view performance information in real-time graphs:

- Current (%FLC)
- Motor Temp (%)
- Motor kW (%)
- Motor kVA (%)
- Motor pf

7.3. Main Menu

The Main Menu button provides access to menus for setting up the MCD 500 for complex applications and for monitoring its performance.

7.3.1. Parameters

Parameters lets you view and change all programmable parameters that control how the MCD 500 operates.

To open Parameters, press the **MAIN MENU** button while viewing the monitoring screens then select Parameters.

To navigate through Parameters:

- to scroll through parameter groups, press the ▲ or ▼ button.
- to view the parameters in a group, press the **OK** button.
- to return to the previous level, press the **BACK** button.
- to close Parameters, press the **BACK** button.

To change a parameter value:

- scroll to the appropriate parameter and press **OK** to enter edit mode.
- to alter the parameter setting, use the **▲** and **▼** buttons.
- to save changes, press **OK**. The setting shown on the display will be saved and the LCP will return to the parameter list.
- to cancel changes, press **BACK**. The LCP will return to the parameter list without saving changes.

7.3.1.2. Parameter Shortcut

The MCD 500 also includes a parameter shortcut, which allows you to directly access a parameter within the Parameters menu.

- To access the parameter shortcut, press the **MAIN MENU** button for three seconds.
- Use the **▲** or **▼** button to select the parameter group.
- Press **OK** to move the cursor.
- Use the **▲** or **▼** button to select the parameter number.

Ready	S1
Parameter shortcut	
Please enter a parameter	
01-01	

7.3.2. Parameter List

1	Primary Mtr Set
1-1	Motor FLC
1-2	Locked Rotor Time
1-3	Start Mode
1-4	Current Limit
1-5	Initial Current
1-6	Start Ramp Time
1-7	Kickstart Level
1-8	Kickstart Time
1-9	Excess Start Time
1-10	Stop Mode
1-11	Stop Time
1-12	Adaptv Control Gain
1-13	Adaptv Start Profile
1-14	Adaptv Stop Profile
1-15	Brake Torque
1-16	Brake Time
2	Protection
2-1	Phase Sequence
2-2	Current Imbalance
2-3	Current Imbal Dly
2-4	Undercurrent
2-5	Undercurrent Dly
2-6	Inst Overcurrent
2-7	Inst Ocrnt Dly
2-8	Frequency Check
2-9	Freq Variation
2-10	Frequency Delay
2-11	Restart Delay
2-12	Motor Temp Check

3	Inputs
3-1	Local/Remote
3-2	Comms in Remote
3-3	Input A Function
3-4	Input A Name
3-5	Input A Trip
3-6	Input A Trip Dly
3-7	Input A Initial Dly
3-8	Remote Reset Logic
4	Outputs
4-1	Relay A Function
4-2	Relay A On Delay
4-3	Relay A Off Delay
4-4	Relay B Function
4-5	Relay B On Delay
4-6	Relay B Off Delay
4-7	Relay C Function
4-8	Relay C On Delay
4-9	Relay C Off Delay
4-10	Low Current Flag
4-11	High Current FLag
4-12	Motor Temp Flag
4-13	Analog Output A
4-14	Analog A Scale
4-15	Analog A Max Adj
4-16	Analog A Min Adj
5	Start/Stop Timers
5-1	Auto-Start Type
5-2	Auto-Start Time
5-3	Auto-Stop Type
5-4	Auto-Stop Time
6	Auto-Reset
6-1	Auto-Reset Action
6-2	Maximum Resets
6-3	Reset Dly Grp A & B
6-4	Reset Delay Grp C
7	Secondary Mtr Set
7-1	Motor FLC-2
7-2	Lock Rotor Time-2
7-3	Start Mode-2
7-4	Current Limit-2
7-5	Initial Crnt-2
7-6	Start Ramp-2
7-7	Kickstart Lvl-2
7-8	Kickstart Time-2
7-9	Excess Strt Time-2
7-10	Stop Mode-2
7-11	Stop Time-2
7-12	Adaptv Ctrl Gain-2
7-13	Adaptv Start Prof-2

7-14	Adaptv Stop Prof-2
7-15	Brake Torque-2
7-16	Brake Time-2
8	Display
8-1	Language
8-2	User Scrn Top L
8-3	User Scrn Top R
8-4	User Scrn Btm L
8-5	User Scrn Btm R
8-6	Graph Timebase
8-7	Graph Max Adj
8-8	Graph Min Adj
8-9	Mains Ref Volt
15	Restrict Paramtr
15-1	Access Code
15-2	Adjustment Lock
15-3	Emergency Run
15-4	Current Calibrat
15-5	Main Cont Time
15-6	Bypass Cont Time
15-7	Motor Connection
16	Protection Action
16-1	Motor Overload
16-2	Current Imbalance
16-3	Undercurrent
16-4	Inst Overcurrent
16-5	Frequency
16-6	Heatsink Overtemp
16-7	Excess Start Time
16-8	Input A Trip
16-9	Motor Thermistor
16-10	Starter/Comms
16-11	Network Comms
16-12	Battery/Clock

7.4. 1 – Primary Motor Settings



NB!:

Default settings are marked with *.

The parameters in Primary Motor Settings configure the soft starter to match the connected motor. These parameters describe the motor's operating characteristics and allow the soft starter to model the motor's temperature.

1-1 – Motor FLC

Value:

Model dependent

Function:

Matches the starter to the connected motor's full load current. Set to the full load current (FLC) rating shown on the motor nameplate.

1-2 – Locked Rotor Time

Value:

0:01 - 2:00 (minutes:seconds) * 10 seconds

Function:

Sets the maximum length of time the motor can run at locked rotor current from cold before reaching its maximum temperature. Set according to the motor datasheet.

If this information is not available, we recommend the value should be less than 20 seconds.

1-3 – Start Mode

Options:

Constant Current

Adaptive Control *

Function:

Selects the soft start mode. => Starting Modes on page 25 for more details.

1-4 – Current Limit

Value:

100% - 600% FLC * 350%

Function:

Sets the current limit for constant current and current ramp soft starting, as a percentage of motor full load current. => Starting Modes on page 25 for more details.

1-5 – Initial Current

Value:

100% - 600% FLC * 350%

Function:

Sets the initial start current level for current ramp starting, as a percentage of motor full load current. Set so that the motor begins to accelerate immediately after a start is initiated.

If current ramp starting is not required, set the initial current equal to the current limit. => Starting Modes on page 25 for more details.

1-6 – Start Ramp Time

Value:

1 - 180 (seconds) * 10 seconds

Function:

Sets the total start time for an AAC Adaptive Control start or the ramp time for current ramp starting (from the initial current to the current limit). => Starting Modes on page 25 for more details.

1-7, 1-8 – Kickstart

Parameter 1-7 – Kickstart Level

Value:

100% - 700% FLC * 500%

Function:

Sets the level of the kickstart current.

Parameter 1-8 – Kickstart Time

Value:

0 – 2000 milliseconds

* 0000 milliseconds

Function:

Sets the kickstart duration. A setting of 0 disables kickstart. => Starting Modes on page 25 for more details.

**NB!:**

Kickstart subjects the mechanical equipment to increased torque levels. Ensure the motor, load and couplings can handle the additional torque before using this feature.

1-9 – Excess Start Time

Excess start time is the maximum time the MCD 500 will attempt to start the motor. If the motor does not reach full speed within the programmed limit, the starter will trip. Set for a period slightly longer than required for a normal healthy start. A setting of 0 disables excess start time protection.

Value:

0:00 - 4:00 (minutes:seconds)

* 20 seconds

Function:

Set as required.

1-10 – Stop Mode

Options:

Coast To Stop *

TVR Soft Stop

Adaptive Control

Brake

Function:

Selects the stop mode. => Stopping Modes on page 27 for more details.

1-11 – Stop Time

Value:

0:00 - 4:00 (minutes:seconds)

* 0 seconds

Function:

Sets the time for soft stopping the motor using timed voltage ramp or Adaptive Control (AAC). If a main contactor is installed, the contactor must remain closed until the end of the stop time. Use a programmable output configured to Run to control the main contactor. Sets the total stopping time when using brake. => Stopping Modes on page 27 for more details.

1-12 – Adaptv Control Gain

Value:

1% - 200%

* 75%

Function:

Adjusts the performance of AAC adaptive acceleration control. => AAC Adaptive Acceleration Control on page 26 for more details.

**NOTE**

We recommend leaving the gain setting at the default level unless AAC performance is not satisfactory.

If the motor accelerates or decelerates quickly at the end of a start or stop, increase the gain setting by 5%~10%. If the motor speed fluctuates during starting or stopping, decrease the gain setting slightly.

1-13 – Adaptv Start Profile

Options:

Early Acceleration
 Constant Acceleration *
 Late Acceleration

Function:

Selects which profile the MCD 500 will use for an AAC adaptive acceleration control soft start. => Starting Modes on page 25 for more details.

1-14 – Adaptv Stop Profile

Options:

Early Deceleration
 Constant Deceleration *
 Late Deceleration

Function:

Selects which profile the MCD 500 will use for an AAC adaptive acceleration control soft stop. => Stopping Modes on page 27 for more details.

1-15, 1-16 – Brake

Brake uses DC injection to actively slow the motor. => Stopping Modes on page 27 for more details.

Parameter 1-15 Brake Torque

Value:

20 - 100% * 20%

Function:

Sets the amount of brake torque the MCD 500 will use to slow the motor.

Parameter 1-16 Brake Time

Value:

1 - 30 (seconds) * 1 second

Function:

Sets the duration for DC injection during a braking stop.



NB!:

Parameter 1-16 is used in conjunction with Par. 1-11. => *Brake* for details.

7.5. 2 – Protection

2-1 – Phase Sequence

Value:

Any sequence *
 Positive only
 Negative only

Function:

Selects which phase sequences the soft starter will allow at a start. During its pre-start checks, the starter examines the sequence of the phases at its input terminals and trips if the actual sequence does not match the selected option.

2-2, 2-3 – Current Imbalance

The MCD 500 can be configured to trip if the currents on the three phases vary from each other by more than a specified amount. The imbalance is calculated as the difference between the highest and lowest currents on all three phases, as a percentage of the highest current.

Current imbalance detection is desensitised by 50% during starting and soft stopping.

Parameter 2-2 *Current Imbalance*

Value:

10% - 50% * 30%

Function:

Sets the trip point for current imbalance protection.

Parameter 2-3 *Current Imbal Dly*

Value:

0:00 - 4:00 (minutes:seconds) * 3 seconds

Function:

Slows the MCD 500's response to current imbalance, avoiding trips due to momentary fluctuations.

2-4, 2-5 – Undercurrent

The MCD 500 can be configured to trip if the average current of all three phases drops below a specified level while the motor is running.

Parameter 2-4 *Undercurrent*

Value:

0% - 100% * 20%

Function:

Sets the trip point for undercurrent protection, as a percentage of motor full load current. Set to a level between the motor's normal working range and the motor's magnetising (no load) current (typically 25% to 35% of full load current). A setting of 0% disables undercurrent protection.

Parameter 2-5 *Undercurrent Dly*

Value:

0:00 - 4:00 (minutes:seconds) * 5 seconds

Function:

Slows the MCD 500's response to undercurrent, avoiding trips due to momentary fluctuations.

2-6, 2-7 – Instantaneous Overcurrent

The MCD 500 can be configured to trip if the average current of all three phases exceeds a specified level while the motor is running.

Parameter 2-6 *Inst Overcurrent*

Value:

80% - 600% FLC * 400%

Function:

Sets the trip point for instantaneous overcurrent protection, as a percentage of motor full load current.

Parameter 2-7 *Inst Ocrnt Delay*

Value:

0:00 - 1:00 (minutes:seconds) * 0 seconds

Function:

Slows the MCD 500's response to overcurrent, avoiding trips due to momentary overcurrent events.

2-8, 2-9, 2-10 – Frequency Trip

The MCD 500 monitors mains frequency throughout operation, and can be configured to trip if the frequency varies beyond a specified tolerance.

Parameter 2-8 *Frequency Check*

Value:

Do Not Check
Start Only
Start/Run *
Run Only

Function:

Determines when the starter will monitor for a frequency trip.

Parameter 2-9 *Freq Variation*

Value:

± 2 Hz
± 5 Hz *
± 10 Hz
± 15 Hz

Function:

Selects the soft starter's tolerance for frequency variation.



NB!:

Running a motor outside its specified frequency for long periods can cause damage and premature failure.

Parameter 2-10 *Frequency Delay*

Value:

0:01 - 4:00 (minutes:seconds) * 1 second

Function:

Slows the MCD 500's response to frequency disturbances, avoiding trips due to momentary fluctuations.



NB!:

If the mains frequency drops below 35 Hz or rises above 75 Hz, the starter will trip immediately.

2-11 – Restart Delay

Value:

00:01 - 60:00 (minutes:seconds) * 10 seconds

Function:

The MCD 500 can be configured to force a delay between the end of a stop and the beginning of the next start. During the restart delay period, the display shows the time remaining before another start can be attempted.



NB!:

The restart delay is measured from the end of each stop. Changes to the restart delay setting take effect after the next stop.

2-12 – Motor Temp Check

Value:

Do Not Check *

Check

Function:

Selects whether the MCD 500 will verify the motor has sufficient thermal capacity for a successful start. The soft starter compares the motor's calculated temperature with the temperature rise from the last motor start and only operates if the motor is cool enough to start successfully.

7.6.3 – Inputs

3-1 – Local/Remote

Options:	Lcl/Rmt anytime *	The user can change between local and remote control at any time.
	Local Control Only	All remote inputs are disabled.
	Remote Control Only	Local control buttons (HAND ON , AUTO ON) are disabled.

Function:

Selects when the **AUTO ON** and **HAND ON** buttons can be used to switch to Hand On or Auto On modes.

3-2 – Comms in Remote

Options:

Disable Ctrl in RMT

Enable Ctrl in RMT *

Function:

Selects whether the starter will accept Start, Stop and Reset commands from the serial communication network when in Remote mode. The Force Comms Trip, Local/Remote Control and Test Start commands are always enabled.

3-3 – Input A Function

Options:	Motor Set Select *	The MCD 500 can be configured with two separate sets of motor data. The primary motor data is programmed using Pars. 1-1 to 1-16. The secondary motor data is programmed using Pars. 7-1 to 7-16. To use the secondary motor data, Par. 3-3 must be set to Motor Set Select and 11, 16 must be closed when a start command is given. The MCD 500 checks which motor data to use at a start, and will use that motor data for the entire start/stop cycle.
	Input Trip (N/O)	Input A can be used to trip the soft starter. When Par. 3-3 is set to Input Trip (N/O), a closed circuit across 11, 16 trips the soft starter (=> Pars. 3-5, 3-6, 3-7).
	Input Trip (N/C)	When Par. 3-3 is set to Input Trip (N/C), an open circuit across 11, 16 trips the soft starter (=> Pars. 3-5, 3-6, 3-7).
	Local/Remote Select	Input A can be used to select between local and remote control, instead of using the buttons on the LCP. Selecting this option disables the HAND ON and OFF buttons, and the soft starter will ignore any Local/Remote select command from the serial communications network. An open circuit across the input selects local control and a closed circuit selects remote control.

Emergency Run	To use Input A to select between local and remote control, Par. 3-1 must be set to LCL/RMT Anytime or LCL/RMT when Off. In emergency run the soft starter continues to run until stopped, ignoring all trips and warnings (=> Par. 15-3 for details). Closing the circuit across 11, 16 activates emergency run. Opening the circuit ends emergency run and the MCD 500 stops the motor.
Emergency Stop	The MCD 500 can be commanded to emergency stop the motor, ignoring the soft stop mode set in Par. 1-10. When the circuit across 11, 16 is opened, the soft starter allows the motor to coast to stop.
Jog Forward	Activates jog operation in a forward direction (will operate only in Remote mode).
Jog Reverse	Activates jog operation in reverse direction (will operate only in Remote mode).

Function:
Selects the function of Input A.

3-4 – Input A Name

Options:

Input Trip *	No Flow
Low Pressure	Emergency Stop
High Pressure	Controller
Pump Fault	PLC
Low Level	Vibration Alarm
High Level	

Function:
Selects a message for the LCP to display when Input A is active.

3-5, 3-6, 3-7 – Input A Trip

Parameter 3-5 Input A Trip

Options:

Always Active *	A trip can occur at any time when the soft starter is receiving power.
Operating Only	A trip can occur while the soft starter is running, stopping or starting.
Run Only	A trip can only occur while the soft starter is running.

Function:
Selects when an input trip can occur.

Parameter 3-6 Input A Trip Dly

Value:

0:00 - 4:00 (minutes:seconds)	* 0 seconds
-------------------------------	-------------

Function:
Sets a delay between the input activating and the soft starter tripping.

Parameter 3-7 Input A Initial Dly

Value:

00:00 - 30:00 (minutes:seconds)	* 0 seconds
---------------------------------	-------------

Function:

Sets a delay before an input trip can occur. The initial delay is counted from the time the starter enters the state selected in 3-5.

3-8 – Remote Reset Logic

Options:

Normally Closed *

Normally Open

Function:

Selects whether the MCD 500's remote reset input (terminals 25, 18) is normally open or normally closed.

7.7. 4 – Outputs

4-1 – Relay A Function

Options:	Off	Relay A is not used.
	Main Contactor *	The relay closes when the MCD 500 receives a start command, and remains closed as long as the motor is receiving voltage.
	Run	The relay closes when the starter changes to run state.
	Trip	The relay closes when the starter trips.
	Warning	The relay closes when the starter issues a warning.
	Low Current Flag	The relay closes when the low current flag activates (=> Par. 4-10 <i>Low Current Flag</i>).
	High Current Flag	The relay closes when the high current flag activates (=> Par. 4-11 <i>High Current Flag</i>).
	Motor Temp Flag	The relay closes when the motor temperature flag activates (=> Par. 4-12 <i>Motor Temperature Flag</i>).

Function:

Selects the function of Relay A (normally open).

4-2, 4-3 – Relay A Delays

The MCD 500 can be configured to wait before opening or closing Relay A.

Parameter 4-2 *Relay A On Delay*

Value:

0:00 - 5:00 (minutes:seconds) * 0 seconds

Function:

Sets the delay for closing Relay A.

Parameter 4-3 *Relay A Off Delay*

Value:

0:00 - 5:00 (minutes:seconds) * 0 seconds

Function:

Sets the delay for re-opening Relay A.

4-4~4-9 – Relays B & C

Parameters 4-4~4-9 configure the operation of Relays B and C in the same way as parameters 4-1~4-3 configure Relay A. => Relay A for details.

Relay B is a changeover relay.

- 4-4 *Relay B Function* * Run
- 4-5 *Relay B On Delay*

- 4-6 *Relay B Off Delay*
Relay C is normally open.

- 4-7 *Relay C Function* * Trip
- 4-8 *Relay C On Delay*
- 4-9 *Relay C Off Delay*

4-10, 4-11 – Low Current Flag and High Current Flag

The MCD 500 has low and high current flags to give early warning of abnormal operation. The current flags can be configured to indicate an abnormal current level during operation, between the normal operating level and the undercurrent or instantaneous overcurrent trip levels. The flags can signal the situation to external equipment via one of the programmable outputs. The flags clear when the current returns within the normal operating range by 10% of the programmed motor full load current.

Parameter 4-10 *Low Current Flag*

Value:

1% - 100% FLC * 50%

Function:

Sets the level at which the low current flag operates, as a percentage of motor full load current.

Parameter 4-11 *High Current Flag*

Value:

50% - 600% FLC * 100%

Function:

Sets the level at which the high current flag operates, as a percentage of motor full load current.

4-12 – Motor Temp Flag

The MCD 500 has a motor temperature flag to give early warning of abnormal operation. The flag can indicate that the motor is operating above its normal operating temperature but lower than the overload limit. The flag can signal the situation to external equipment via one of the programmable outputs.

Value:

0% - 160% * 80%

Function:

Sets the level at which the motor temperature flag operates, as a percentage of the motor's thermal capacity.

4-13~4-16 – Analog Output A

The MCD 500 has an analog output, which can be connected to associated equipment to monitor motor performance.

Parameter 4-13 *Analog Output A*

Options:	Current (% FLC) *	Current as a percentage of motor full load current.
	Motor Temp (%)	Motor temperature as a percentage of the motor service factor (calculated by the soft starter's thermal model).
	Motor kW (%)	Motor kilowatts. 100% is motor FLC (Par. 1-1) multiplied by mains reference voltage (Par. 8-9). Power factor is assumed to be 1.0.
		$\frac{\sqrt{3} \cdot V \cdot I_{FLC} \cdot pf}{1000}$

Motor kVA (%)	Motor kilovolt amperes. 100% is motor FLC (Par. 1-1) multiplied by mains reference voltage (Par. 8-9).
	$\frac{\sqrt{3} \cdot V \cdot I_{FLC}}{1000}$
Motor pf	Motor power factor, measured by the soft starter.

Function:

Selects which information will be reported via analog output A.

Parameter 4-14 Analog A Scale

Options:

0-20 mA

4-20 mA *

Function:

Selects the range of the output.

Parameter 4-15 Analog A Max Adj

Value:

0% - 600% * 100%

Function:

Calibrates the upper limit of the analog output to match the signal measured on an external current measuring device.

Parameter 4-16 Analog A Min Adj

Value:

0% - 600% * 0%

Function:

Calibrates the lower limit of the analog output to match the signal measured on an external current measuring device.

7.8. 5 – Start/Stop Timers



The auto-start timer overrides any other form of control. The motor may start without warning.

5-1, 5-2 – Auto-Start

Parameter 5-1 Auto-Start Type

Options:	Off *	The soft starter will not auto-start.
	Timer	The soft starter will auto-start after a delay from the next stop, as specified in Par. 5-2.
	Clock	The soft starter will auto-start at the time programmed in Par. 5-2.

Function:

Selects whether the soft starter will auto-start after a specified delay, or at a time of day.

Parameter 5-2 Auto-Start Time

Value:

00:01 - 24:00 (hours:minutes) * 1 minute

Function:

Sets the time for the soft starter to auto-start, in 24 hour clock format.

Sets how many times the soft starter will auto-reset, if it continues to trip. The reset counter increases by one each time the soft starter auto-resets, and decreases by one after each successful start/stop cycle.

6-3, 6-4 – Auto-Reset Delay

The MCD 500 can be configured to wait before auto-resetting a trip. Separate delays can be set for trips in Groups A and B, or in Group C.

Parameter 6-3 *Reset Dly Grp A & B*

Value:

00:05 - 15:00 (minutes:seconds) * 5 seconds

Function:

Sets the delay for Group A and Group B trips.

Parameter 6-4 *Reset Dly Grp C*

Value:

5 - 60 (minutes) * 5 minutes

Function:

Sets the delay for Group C trips.

7.10. 7 – Secondary Motor Set

7-1~7-16 – Secondary Motor Set

=> Primary Motor Set (parameters 1-1~1-17) for details.

Parameter 7-1 *Motor FLC-2*

Value:

Model dependent

Function:

Sets the secondary motor's full load current.

Parameter 7-2 *Locked Rotor Time-2*

Value:

0:01 - 2:00 (minutes:seconds) * 10 seconds

Function:

Sets the secondary motor's locked rotor time.

Parameter 7-3 *Start Mode-2*

Options:

Constant Current

Adaptive Control *

Function:

Selects the start mode for the secondary motor.

Parameter 7-4 *Current Limit-2*

Value:

100% - 600% FLC * 350%

Function:

Sets the current limit for constant current starting.

Parameter 7-5 Initial Crnt-2

Value:

100% - 600% * 350%

Function:

Sets the initial start current level for current ramp or constant current starting.

Parameter 7-6 Start Ramp Time-2

Value:

1 - 180 (seconds) * 10 seconds

Function:

Sets the total start time for an AAC adaptive acceleration control start or the ramp time for current ramp starting (from the initial current to the current limit).

Parameter 7-7 Kickstart Lvl-2

Value:

100% - 700% FLC * 500%

Function:

Sets the level of the kickstart current.

Parameter 7-8 Kickstart Time-2

Value:

0 - 2000 (milliseconds) * 0000 milliseconds

Function:

Sets the kickstart duration.

Parameter 7-9 Excess Start Time-2

Value:

0:00 - 4:00 (minutes:seconds) * 20 seconds

Function:

Sets the excess start time for the secondary motor.

Parameter 7-10 Stop Mode-2

Options:

Coast to Stop *

TVR Soft Stop

Adaptive Control

Brake

Function:

Selects the stop mode for the secondary motor.

Parameter 7-11 Stop Time-2

Value:

0:00 - 4:00 (minutes:seconds) * 0 seconds

Function:

Sets the stop time.

Parameter 7-12 Adptv Ctrl Gain-2

Value:

1% - 200% * 75%

Function:

Adjusts the performance of an AAC adaptive acceleration control.

Parameter 7-13 Adptv Start Prof-2

Options:

Early Acceleration

Constant Acceleration *

Late Acceleration

Function:

Selects the start profile for an AAC adaptive acceleration control soft start.

Parameter 7-14 Adptv Stop Prof-2

Options:

Early Deceleration

Constant Deceleration *

Late Deceleration

Function:

Selects the stop profile for an AAC adaptive acceleration control stop.

Parameter 7-15 Brake Torque-2

Value:

20% - 100% * 20%

Function:

Sets the amount of brake torque the MCD 500 will use to slow the motor.

Parameter 7-16 Brake Time-2

Value:

1 - 30 (seconds) * 1 second

Function:

Sets the duration for DC injection during a braking stop.

7.11. 8 – Display

8-1 – Language

Options:

English *

Chinese (中文)

Spanish (Español)

German (Deutsch)

Portuguese (Português)

French (Français)

Italian (Italiano)

Russian (Русский)

Function:

Selects which language the LCP will use to display messages and feedback.

8-2~8-5 – User Programmable Screen

Options:	Blank	Displays no data in the selected area, allowing long messages to be shown without overlapping.
	Starter State	The starter's operating state (starting, running, stopping or tripped). Only available for 'Top L' & 'Btm L'
	Motor Current	The average current measured on three phases.

**NB!:**

This adjustment affects all current-based functions.

15-5 – Main Cont Time

Value:

100 – 2000 milliseconds

* 150 milliseconds

Function:

Sets the delay period between the starter switching the main contactor output (terminals 13, 14) and beginning the pre-start checks (before a start) or entering the not ready state (after a stop). Set according to the specifications of the main contactor used.

15-6 – Bypass Cont Time

Value:

100 – 2000 milliseconds

* 150 milliseconds

Function:

Sets the delay period before the starter switches the bypass contactor output (terminals 21, 22, 24) and transitions from starting to running, after the motor voltage has reached 100% in a start; or before the starter commences the stop ramp, after a stop command. Set according to the specifications of the bypass contactor used.

15-7 – Motor Connection

Options:

Auto-Detect *

In-line

Inside Delta

Function:

Selects whether the soft starter will automatically detect the format of the connection to the motor.

7.13. 16 – Protection Action

16-1~16-12 – Protection Action

Options:

Trip Starter *

Warn and Log

Log Only

Function:

Selects the soft starter's response to each protection.

- 16-1 *Motor Overload*
- 16-2 *Current Imbalance*
- 16-3 *Undercurrent*
- 16-4 *Inst Overcurrent*
- 16-5 *Frequency*
- 16-6 *Heatsink Overtemp*
- 16-7 *Excess Start Time*
- 16-8 *Input A Trip*
- 16-9 *Motor Thermistor*
- 16-10 *Starter/Comms*
- 16-11 *Network Comms*

- 16-12 *Battery/Clock*

7.14. 20 – Factory Parameters

These parameters are restricted for Factory use and are not available to the user.

8. Tools

To access Tools, open the Main Menu, scroll to Tools and press **OK**.



NB!:

The simulation tools and counter resets are also protected by the security access code.

The default access code is 0000.

8.1. Set Date and Time

To set the date and time:

1. Open the Tools Menu.
2. Scroll to the date/time screen.
3. Press the **OK** button to enter edit mode.
4. Press the **OK** button to select which part of the date or time to edit.
5. Use the **▲** and **▼** buttons to change the value.

To save changes, press the **OK** button repeatedly. The MCD 500 will confirm the changes.

To cancel changes, press the **BACK** button repeatedly.

8.2. Load/Save Settings

The MCD 500 includes options to:

- Load defaults: Load the MCD 500's parameters with default values
- Load User Set 1: Reload previously saved parameter settings from an internal file
- Save User Set 1: Save the current parameter settings to an internal file

In addition to the factory default values file, the MCD 500 can store a user-defined parameter file.

This file contains default values until a user file is saved.

To load or save parameter settings:

1. Open the Tools Menu.
2. Use the **▼** button to select the required function, then press the **OK** button.
3. At the confirmation prompt, select YES to confirm or NO to cancel and then **OK** to load/save the selection.

Tools
Load Defaults
Load User Set 1
Save User Set 1
Load Defaults
No
Yes

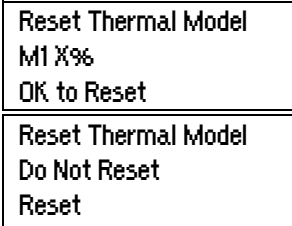
When the action has been completed, the screen will briefly display a confirmation message, then return to the status screens.

8.3. Reset Thermal Model

The MCD 500's advanced thermal modelling software constantly monitors the motor's performance. This allows the MCD 500 to calculate the motor's temperature and ability to start successfully at any time.

The thermal model can be reset if required.

1. Open Tools.
2. Scroll to Reset Thermal Model and press **OK**.
3. At the confirmation prompt, press **OK** to confirm then enter the access code, or press **BACK** to cancel the action.
4. Select Reset or Do Not Reset, then press **OK**. When the thermal model has been reset, the MCD 500 will return to the previous screen.



Adjusting the motor thermal model may compromise motor life and should only be done in the case of emergency.

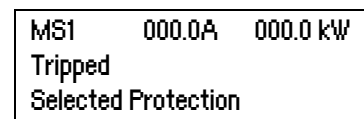
8.4. Protection Simulation

Software simulation functions let you test the soft starter's operation and control circuits without connecting the soft starter to mains voltage.

The MCD 500 can simulate each different protection, in order to confirm that the soft starter is responding correctly and reporting the situation on the display and across the communication network.

To use the protection simulation:

1. Open the Main Menu.
2. Scroll to Protection Sim and press **OK**.
3. Use the ▲ and ▼ buttons to select the protection you want to simulate.
4. Press **OK** to simulate the selected protection.
5. The screen is displayed while **OK** is pressed. The soft starter's response depends on the Protection Action setting (parameter group 16).
6. Press **BACK** to return to the simulation list.
7. Use ▲ or ▼ to select another simulation, or press **BACK** to return to the Main Menu.



NB!:

If the protection trips the soft starter, reset before simulating another protection. If the protection action is set to 'Warning or Log', no reset is required.

If the protection is set to 'Warning & Log', the warning message can be viewed only while the '**OK**' button is pressed.

If the protection is set to 'Log only', nothing appears on the screen but an entry will appear in the log.

8.5. Output Signal Simulation

The LCP allows the user to simulate output signalling in order to confirm that the output relays are operating correctly.



NB!:

To test operation of the flags (motor temperature and low/high current), set an output relay to the appropriate function and monitor the relay's behaviour.

To use the signal simulation:

1. Open the Main Menu.
2. Scroll to Output Signal Sim and press **OK**, then enter the access code.
3. Use the **▲** and **▼** buttons to select a simulation, then press **OK**.
4. Use the **▲** and **▼** buttons to turn the signal on and off.
To confirm correct operation, monitor the state of the output.
5. Press **BACK** to return to the simulation list.

Prog Relay A Off On

8.6. Digital I/O State

This screen shows the current status of the Digital I/O in order. The screen shot shows the stop input (17) as closed (1) and the start, reset and Input A inputs (15, 25, 11) as open (0). Relay A (13, 14) is closed and relays B and C (21, 22, 24 and 33, 34) are open.

Digital I/O State Inputs: 01000000 Outputs: 10000000

8.7. Temp Sensors State

This screen shows the state of the motor thermistor.
The screen shot shows the thermistor state as O (open).

Temp Sensors State Thermistor: O S = Shrt H=Hot C=Cld O=Opn
--

8.8. Alarm Log

The **ALARM LOG** button opens the Alarm Logs, which contains a Trip Log, Event Log, and Counters which store information on the MCD 500's operating history.

8.8.1. Trip Log

The trip log stores details of the eight most recent trips, including the date and time the trip happened. Trip 1 is the most recent and trip 8 is the oldest stored trip.

To open the Trip Log:

1. Open the Alarm Logs.
2. Scroll to Trip Log and press **OK**.
3. Use the **▲** and **▼** buttons to select a trip to view, and press **OK** to display details.

To close the log and return to the main display, press **BACK**.

8.8.2. Event Log

The event log stores time-stamped details of the starter's 99 most recent events (actions, warnings and trips), including the date and time of the event. Event 1 is the most recent and event 99 is the oldest stored event.

To open the Event Log:

1. Open the Alarm Logs.
2. Scroll to Event Log and press **OK**.
3. Use the **▲** and **▼** buttons to select an event to view, and press **OK** to display details.

To close the log and return to the main display, press **BACK**.

8.8.3. Counters

The performance counters store statistics on the starter's operation:

- Hours run (lifetime and since counter last reset)
- Number of starts (lifetime and since counter last reset)
- Motor kWh (lifetime and since counter last reset)
- Number of times the thermal model has been reset

The resettable counters (hours run, starts and motor kWh) can only be reset if the correct access code is entered.

To view the counters:

1. Open the Alarm Logs.
2. Scroll to Counters and press **OK**.
3. Use the **▲** and **▼** buttons to scroll through the counters. Press **OK** to view details.
4. To reset a counter, press **OK** then enter the access code. Select Reset, then press **OK** to confirm.

To close the counter and return to the Alarm Logs, press **BACK**.

9. Troubleshooting

When a protection condition is detected, the MCD 500 will write this to the event log and may also trip or issue a warning. The soft starter's response to some protections may depend on the Protection Action settings (parameter group 16).

If the MCD 500 trips you will need to reset the soft starter before restarting. If the MCD 500 has issued a warning, the soft starter will reset itself once the cause of the warning has been resolved.

Some protections cause a fatal trip. This response is pre-defined and cannot be overridden. These protection mechanisms are designed to protect the soft starter, or can be caused by a fault within the soft starter.

9.1. Trip Messages

This table lists soft starter's protection mechanisms and the probable cause of the trip. Some of these can be adjusted using parameter group 2 *Protection* and parameter group 16 *Protection Action*, other settings are built-in system protections and cannot be set or adjusted.


Display	Possible cause/Suggested solution
Battery/Clock	A verification error has occurred on the real time clock, or the backup battery voltage is low. If the battery is low and the power is off, date/time settings will be lost. Reprogram the clock. Related Pars.: 16-12
Current Imbalance	Current imbalance can be caused by problems with the motor, the environment or the installation, such as: <ul style="list-style-type: none"> • An imbalance in the incoming mains voltage • A problem with the motor windings • A light load on the motor Current imbalance can also be caused by incorrect cabling between the external bypass relay and the soft starter or an internal problem with the soft starter, particularly an SCR that has failed open circuit. A failed SCR can only be definitely diagnosed by replacing the SCR and checking the starter's performance. Related Pars.: 2-2, 2-3, 16-2
Excess Start Time	Excess start time trip can occur in the following conditions: <ul style="list-style-type: none"> • The FLC setting is wrong • The Current Limit has been set too low • The Start Ramp Time has been set greater than the Excess Start Time setting The Start Ramp Time is set too short for a high inertia load when using adaptive acceleration control Related Pars.: 1-1, 1-6, 1-4, 1-9, 7-9, 7-1, 7-6, 7-4, 16-7
FLC Too High	The MCD 500 can support higher motor FLC values when connected to the motor using inside delta configuration rather than in-line connection. If the soft starter is connected in-line but the selected motor FLC is above the in-line maximum, the soft starter will trip at start. Related Pars.: 1-1, 7-1
Frequency	The mains frequency has gone beyond the specified range. Check for other equipment in the area that could be affecting the mains supply (particularly variable speed drives). If the MCD 500 is connected to a generator set supply, the generator may be too small or could have a speed regulation problem. Related Pars.: 2-8, 2-9, 2-10, 16-5

Heatsink Overtemp	<p>Check if cooling fans are operating. If mounted in an enclosure check if ventilation is adequate.</p> <p>On models with internal bypass, the cooling fans will operate:</p> <ul style="list-style-type: none"> • During the Start sequence and for 10 minutes after transition to Run. • For 10 minutes after Stop. <p>Models without internal bypass, will operate the cooling fans from a Start until 10 minutes after a Stop.</p> <p>Related Pars.: 16-6</p>
Input A Trip	<p>Identify and resolve the condition which caused Input A to activate.</p> <p>Related Pars.: 3-3, 3-4, 3-5, 3-6, 3-7, 16-8</p>
Inst Overcurrent	<p>The motor has experienced a sharp rise in motor current, probably caused by a locked rotor condition (shearpin) while running. This may indicate a jammed load.</p> <p>Related Pars.: 2-6, 2-7, 16-4</p>
Internal Fault X	<p>The MCD 500 has tripped on an internal fault. Contact your local supplier with the fault code (X).</p> <p>Related Pars.: None</p>
L1 Phase Loss L2 Phase Loss L3 Phase Loss	<p>During prestart checks the starter has detected a phase loss as indicated.</p> <p>In run state, the starter has detected that the current on the affected phase has dropped below 3.3% of the programmed motor FLC for more than 1 second, indicating that either the incoming phase or connection to the motor has been lost.</p> <p>Check the supply and the input and output connections at the starter and at the motor end.</p> <p>Phase loss can also be caused by a failed SCR, particularly an SCR that has failed open circuit. A failed SCR can only be definitely diagnosed by replacing the SCR and checking the starter's performance.</p> <p>Related Pars.: None</p>
L1-T1 Shorted L2-T2 Shorted L3-T3 Shorted	<p>During prestart checks the starter has detected a shorted SCR or a short within the bypass contactor as indicated.</p> <p>Related Pars.: none</p>
Motor Overload	<p>The motor has reached its maximum thermal capacity. Overload can be caused by:</p> <ul style="list-style-type: none"> • The soft starter protection settings not matching the motor thermal capacity. • Excessive starts per hour • Excessive throughput • Damage to the motor windings. <p>Resolve the cause of the overload and allow the motor to cool.</p> <p>Related Pars.: 1-1, 1-2, 1-3, 1-4, 16-1</p>
Motor Connection	<p>The motor is not connected correctly to the soft starter for inline or inside delta use.</p> <ul style="list-style-type: none"> • Check individual motor connections to the soft starter for power circuit continuity. • Check connections at the motor terminal box. <p>Related Pars.: 15-7</p>
Motor Thermistor	<p>The motor thermistor input has been enabled and:</p> <ul style="list-style-type: none"> • The resistance at the thermistor input has exceeded 3.6 kΩ for more than one second. • The motor winding has overheated. Identify the cause of the overheating and allow the motor to cool before restarting. • The motor thermistor input has been open. <p>Note: If a valid motor thermistor is no longer used, a 1.2 kΩ resistor must be fitted across terminals 05, 06.</p> <p>Related Pars.: 16-9</p>
Network Comms	<p>The network master has sent a trip command to the starter, or there may be a network communication problem.</p> <p>Check the network for causes of communication inactivity.</p> <p>Related Pars.: 16-11</p>

Parameter out of Range	<ul style="list-style-type: none"> A parameter value is outside the valid range. <p>The LCP will indicate the first parameter which is out of range. Press RESET to go to the parameter and adjust the setting.</p> <p>Related Pars.: None</p>
Phase Sequence	<p>The phase sequence on the soft starter's input terminals (L1, L2, L3) is not valid. Check the phase sequence on L1, L2, L3 and ensure the setting in Par. 2-1 is suitable for the installation.</p> <p>Related Pars.: 2-1</p>
Power Loss	<p>The starter is not receiving mains supply on one or more phases when a Start Command is given.</p> <p>Check that the main contactor closes when a start command is given, and remains closed until the end of a soft stop.</p> <p>Related Pars.: 15-5</p>
Secondary Motor Fail	<p>Control voltage has been applied to the MCD 500 with a link across input A (11, 16). The default function for input A is Motor Set Select. Remove the link, change the setting for Par. 3-3 then replace the link.</p> <p>Related Pars.: 3-3</p>
Starter/Comms	<ul style="list-style-type: none"> There is a problem with the connection between the soft starter and the optional communications module. Remove and reinstall the module. If the problem persists, contact your local distributor. There is an internal communications error within the soft starter. Contact your local distributor. <p>Related Pars.: 16-10</p>
Thermistor Cct	<p>The thermistor input has been enabled and:</p> <ul style="list-style-type: none"> The resistance at the input has fallen below 20 Ω (the cold resistance of most thermistors will be over this value) or A short circuit has occurred. Check and resolve this condition. <p>Check that a PT100 (RTD) is not connected to 05, 06.</p> <p>Related Pars.: None.</p>
Time - Overcurrent	<p>The MCD 500 is internally bypassed and has drawn high current during running. (The 10A protection curve trip has been reached or the motor current has risen to 600% of the motor FLC setting.)</p> <p>Related Pars.: None</p>
Undercurrent	<p>The motor has experienced a sharp drop in current, caused by loss of load. Causes can include broken components (shafts, belts or couplings), or a pump running dry.</p> <p>Related Pars.: 2-4, 2-5, 16-3</p>
Unsupported Option	<p>The selected function is not available (e.g. jog is not supported in inside delta configuration).</p> <p>Related Pars.: None</p>

9.2. General Faults

This table describes situations where the soft starter does not operate as expected but does not trip or give a warning.

Symptom	Probable Cause
Soft starter does not respond to commands.	<ul style="list-style-type: none"> • If the soft starter does not respond to the RESET button on the LCP: <ul style="list-style-type: none"> - The soft starter may be in Auto On mode and will only accept commands from the remote control inputs. In Auto On mode, the Auto On LED on the LCP is active. Press the HAND ON or OFF button to enable control via the LCP (this will also send a start or stop command to the MCD 500). • If the soft starter does not respond to commands from the control inputs: <ul style="list-style-type: none"> - The soft starter may be in Hand On mode and will only accept commands from the LCP. When the soft starter is in Hand On control mode, the Off or Hand On LED on the LCP is active. To change to Auto On mode, press the AUTO ON button once. - The control wiring may be incorrect. Check that the remote start, stop and reset inputs are configured correctly (=> <i>Control Wiring</i> for details). - The signals to the remote inputs may be incorrect. Test the signalling by activating each input signal in turn. The appropriate remote control input LED should activate on the LCP. - The soft starter will only execute a start command from the remote inputs if the remote reset input is activated. Check that the remote reset input is also active (the Reset LED on the starter will be on). • If the soft starter does not respond to a start command from either the local or remote controls: <ul style="list-style-type: none"> - The soft starter may be waiting for the restart delay to elapse. The length of the restart delay is controlled by Par. 2-11 <i>Restart Delay</i>. - The motor may be too hot to permit a start. If Par. 2-12 <i>Motor Temperature Check</i> is set to Check, the soft starter will only permit a start when it calculates that the motor has sufficient thermal capacity to complete the start successfully. Wait for the motor to cool before attempting another start. - The emergency stop function may be active. If Par. 3-3 is set to Emergency Stop and there is an open circuit on the corresponding input, the MCD 500 will not start. If the emergency stop situation has been resolved, close the circuit on the input.
The soft starter does not control the motor correctly during starting.	<ul style="list-style-type: none"> • Start performance may be unstable when using a low Motor Full Load Current setting (Par. 1-1). This can affect use on a small test motor with full load current between 5 A and 50 A. • Power factor correction (PFC) capacitors must be installed on the supply side of the soft starter. To control a dedicated PFC capacitor contactor, connect the contactor to run relay terminals.
Motor does not reach full speed.	<ul style="list-style-type: none"> • If the start current is too low, the motor will not produce enough torque to accelerate to full speed. The soft starter may trip on excess start time. <p> NB!: Make sure the motor starting parameters are appropriate for the application and that you are using the intended motor starting</p>

	<p>profile. If Par. 3-3 is set to Motor Set Select, check that the corresponding input is in the expected state.</p> <ul style="list-style-type: none"> The load may be jammed. Check the load for severe overloading or a locked rotor situation.
Erratic motor operation.	<ul style="list-style-type: none"> The SCRs in the MCD 500 require at least 5 A of current to latch. If you are testing the soft starter on a motor with full load current less than 5 A, the SCRs may not latch correctly.
Soft stop ends too quickly.	<ul style="list-style-type: none"> The soft stop settings may not be appropriate for the motor and load. Review the settings of Pars. 1-10, 1-11, 7-10 and 7-11. If the motor is very lightly loaded, soft stop will have limited effect.
AAC adaptive acceleration control, DC brake and Jog functions not working	<ul style="list-style-type: none"> These features are only available with in-line installation. If the MCD 500 is installed inside delta, these features will not operate.
A reset does not occur after an Auto-Reset, when using a remote 2-wire control.	<ul style="list-style-type: none"> The remote 2-wire start signal must be removed and reapplied for a re-start.
Remote start/stop command is overriding Auto Start/Stop settings when using remote 2-wire control.	<ul style="list-style-type: none"> Auto Start/Stop function should only be used in HAND ON mode or in tandem with HAND OFF mode, 3 and 4-wire control.
After selecting AAC the motor used an ordinary start and/or the second start was different to the first.	<ul style="list-style-type: none"> The first AAC start is current limit so that the starter can learn from the motor characteristics. Subsequent starts use AAC.
Non-resettable THERMISTOR FAIL trip, when there is a link between Thermistor input 05, 06 or when the motor thermistor connected between 05, 06 is permanently removed.	<ul style="list-style-type: none"> The thermistor input is enabled once a link is fitted and short circuit protection has activated. <ul style="list-style-type: none"> Remove the link then load the default parameter set. This will disable the thermistor input and clear the trip. Place a 1k2 ohm resistor across the thermistor input. Turn thermistor protection to 'Log only' (parameter 16I).
Parameter settings cannot be stored.	<ul style="list-style-type: none"> Make sure you are saving the new value by pressing the OK button after adjusting a parameter setting. If you press BACK, the change will not be saved. Check that the adjustment lock (Par. 15-2) is set to Read/Write. If the adjustment lock is on, settings can be viewed but not changed. You need to know the security access code to change the adjustment lock setting. The EEPROM may be faulty on the Main Control PCB. A faulty EEPROM will also trip the soft starter, and the LCP will display the message Par Out of Range. Contact your local supplier for advice.

10. Specifications

Supply

Mains voltage (L1, L2, L3)

MCD5-xxxx-T5 200 VAC ~ 525 VAC ($\pm 10\%$)

MCD5-xxxx-T7 380 VAC ~ 600 VAC ($\pm 10\%$) (in-line or inside delta connection)

MCD5-xxxx-T7 380 VAC ~ 690 VAC ($\pm 10\%$) (earthed star supply system only)

Control voltage (A4, A5, A6)

CV1 (A5, A6) 24 VAC/VDC ($\pm 20\%$)

CV2 (A5, A6) 110~120 VAC (+ 10% / - 15%)

CV2 (A4, A6) 220~240 VAC (+ 10% / - 15%)

Current consumption (maximum)

CV1 2.8 A

CV2 (110~120 VAC) 1 A

CV2 (220~240 VAC) 500 mA

Mains frequency 50/60 Hz ($\pm 10\%$)

Rated insulation voltage to earth 600 VAC

Rated impulse withstand voltage 4 kV

Form designation Bypassed or continuous, semiconductor motor starter form 1

Short circuit capability

Coordination with semiconductor fuses Type 2

Coordination with HRC fuses Type 1

MCD5-0021B to MCD5-0105B prospective current 10 kA

MCD5-0131B to MCD5-0245C prospective current 18 kA

MCD5-0360C to MCD5-0927C prospective current 85 kA

MCD5-1200C to MCD5-1600C prospective current 100 kA

Electromagnetic capability (compliant with EU Directive 89/336/EEC)

EMC Emissions..... IEC 60947-4-2 Class B and Lloyds Marine No 1 Specification

EMC Immunity..... IEC 60947-4-2

Inputs

Input Rating Active 24 VDC, 8 mA approx

Start (15, 16) Normally open

Stop (17, 18) Normally closed

Reset (25, 18) Normally closed

Programmable Input (11, 16) Normally open

Motor Thermistor (05, 06) Trip >3.6 k Ω , reset <1.6k Ω

Outputs

Relay Outputs 10A @ 250 VAC resistive, 5A @ 250 VAC AC15 pf 0.3

Programmable Outputs

Relay A (13, 14) Normally open

Relay B (21, 22, 24) Changeover

Relay C (33, 34) Normally open

Analog Output (07, 08) 0-20 mA or 4-20 mA (selectable)

Maximum load 600 Ω (12 VDC @ 20 mA)

Accuracy $\pm 5\%$

24 VDC Output (16, 08) Maximum load..... 200 mA

Accuracy $\pm 10\%$

Environmental

Protection

MCD5-0021B ~ MCD5-0105B IP20 & NEMA, UL Indoor Type 1

MCD5-0131B ~ MCD5-1600C IP00, UL Indoor Open Type

Operating temperature -10 °C to 60 °C, above 40 °C with derating

Storage temperature - 25 °C to + 60 °C

Operating Altitude..... 0 - 1000 m, above 1000 m with derating

Humidity 5% to 95% Relative Humidity
 Pollution degree Pollution Degree 3

Heat Dissipation

During start 4.5 watts per ampere
 During run
 MCD5-0021B ~ MCD5-0053B ≤ 39 watts approx
 MCD5-0068B ~ MCD5-0105B ≤ 51 watts approx
 MCD5-0131B ~ MCD5-0215B ≤ 120 watts approx
 MCD5-0245C ~ MCD5-0927C 4.5 watts per ampere approx
 MCD5-1200C ~ MCD5-1600C 4.5 watts per ampere approx

Certification

C✓ IEC 60947-4-2
 UL/ C-UL UL 508
 MCD5-0021B ~ MCD5-0105BIP20 & NEMA, UL Indoor Type 1
 MCD5-0131B ~ MCD5-1600CIP00, UL Indoor Open Type
 CE IEC 60947-4-2
 CCC (Pending) GB 14048-6
 Marine (Pending)(MCD5-0021B ~ MCD5-0215B only) Lloyds Marine No 1 Specification
 RoHS Compliant with EU Directive 2002/95/EC

10.1. Accessories

10.1.1. Communication Modules

MCD 500 soft starters support network communication using the Profibus, DeviceNet and Modbus RTU protocols, via an easy-to-install communications module.

- Modbus Module: 175G9000
- Profibus Module: 175G9001
- DeviceNet Module: 175G9002

10.1.2. PC Software

MCD PC Software can be used in conjunction with a communications module to provide the following functionality for networks of up to 99 soft starters.

Feature	MCD 201	MCD 202	MCD 3000	MCD 500
Operational Control (Start, Stop, Reset, Quick Stop)	●	●	●	●
Starter status monitoring (Ready, Starting, Running, Stopping, Tripped)	●	●	●	●
Performance monitoring (motor current, motor temperature)		●	●	●
Upload parameter settings			●	●
Download parameter settings			●	●

10.1.3. Finger Guard Kit

Finger guards may be specified for personnel safety and can be used on MCD 500 soft starter models 0131B~1600C. Finger guards fit over the soft starter terminals to prevent accidental contact with live terminals. Finger guards provide IP20 protection.

- MCD5-0068B ~ MCD5-0105B: 175G5662
- MCD5-0131B ~ MCD5-0215B: 175G5663
- MCD5-0245C ~ MCD5-0927C: 175G5664
- MCD5-1200C ~ MCD5-1600C: 175G5665

10.2. Model Selection



NB!:

The start current requirements suggested in the table below are typical and appropriate in most circumstances. However, start torque requirements and performance of motors and machines do vary. Please contact Danfoss if your application involves extremes of operation (such as frequent starting, regular stalls, jams or overloads, high altitude or temperature extremes). Danfoss is always happy to discuss the most appropriate solution for your situation.

To select the correct MCD 500 model:

1. Determine whether the application requires a normal duty or heavy duty rating. The table below can be used as a guide.
2. Select an MCD 500 model with full load current greater than that of the motor at the appropriate duty.

Application	Duty
General and Water	
Centrifugal pump	Normal
Compressor (screw, unloaded)	Normal
Compressor (reciprocating)	Heavy
Conveyor	Normal
Fan (damped)	Normal
Fan (undamped)	Heavy
Mixer	Heavy
Positive displacement pump	Normal
Submersible pump	Normal
Metals and Mining	
Belt conveyor	Heavy
Dust collector	Normal
Grinder	Normal
Hammer mill	Heavy
Rock crusher	Normal
Roller conveyor	Normal
Roller mill	Heavy
Tumbler	Normal
Wire draw machine	Heavy
Food Processing	
Bottle washer	Normal
Centrifuge	Normal
Dryer	Heavy
Mill	Heavy
Palletiser	Heavy
Separator	Heavy
Slicer	Normal

Pulp and Paper Dryer Re-pulper Shredder	Heavy Heavy Heavy
Petrochemical Ball mill Centrifuge Extruder Screw conveyor	Heavy Normal Heavy Normal
Transport and Machine Tool Ball mill Grinder Material conveyor Palletiser Press Roller mill Rotary table	Heavy Normal Normal Heavy Normal Heavy Normal
Lumber and Wood products Bandsaw Chipper Circular saw Debarker Edger Hydraulic power pack Planer Sander	Heavy Heavy Normal Normal Normal Normal Normal Normal